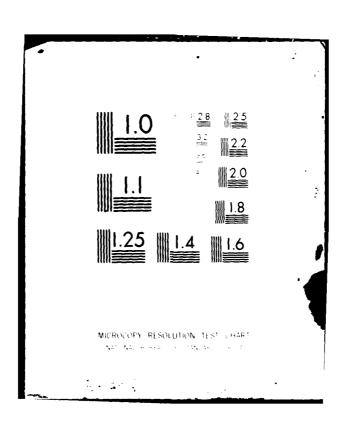
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# TOPICS IN OPTICAL MATERIALS AND DEVICE RESEARCH - II

Parke Mathematical Laboratories

- T. B. Barrett
- H. Haskel
- C. E. Ryan
- R. V. Wood
- S. P. Yukon

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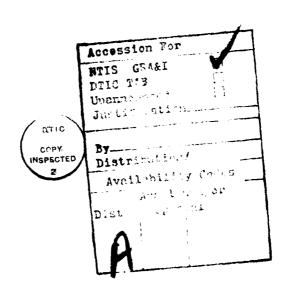
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### Foreword

This report is the first part of a two-part final report for Contract F19628-78-C-0089. Part II, dealing with the construction and operation of a IEEE-488 (GPIB) interface for the Nicolet 1080 computer is entitled: GPIB Interface for the Nicolet 1080 Computer.

The following individuals have contributed to results reported on in these reports.

Laurence Armour - Consultant to PML
Dean Bandes - Parke Mathematical Laboratories
Theodore B. Barrett - Parke Mathematical Laboratories
George Bartley - Consultant to PML
Carl Cioffi - Parke Mathematical Laboratories
Arthur Harrison - Parke Mathematical Laboratories
Haim Haskal - Consultant to PML
Charles Ryan - Consultant to PML
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# TABLE OF CONTENTS

Preface	1
Section I - Fiber Optic Wavelength Multiplexers (H.Haskal)	3
Section II - Charge Coupled Device Fabrication Steps (C.E. Ryan)	5
Section III - Generation of Short, High-Energy Pulses (R. Van Wood)	15
Section IV - Theory of Optical Time Domain Reflectometry From Perturbed Fibers (S.P. Yukon)	16
Attachment A - Fresnel Zone Plates for Wavelength Demultiplexing	30
Attachment B - Theory of Optical Time Domain  Reflectometry from Perturbed Fibers	46

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### Preface (to Part I)

This report, composed of four sections, provides a summary of work accomplished under this contract in four diverse areas of optical transmission and processing. Briefly, these sections consist of:

- I. A description of optic of wavelength multiplexing. This section includes as an attachment a report on the subject presented at the Conference on the Physics of Fiber Optics (Chicago, April 1980).
- II. A summary of techniques for the fabrication of charge coupled devices (CCD); with emphasis on the selection and evaluation of wafers, oxidation of wafers and the preparation of fibers on the oxidized wafers.
- III. A short summary of work which was done on the development of a device to produce short duration, high energy optical pulses.
- IV. The theoretical development of optical time domain reflectometry applied to optical waveguides with weak static perturbations. This section also includes as an attachment a report on the subject presented at the Chicago Conference.

Other work for this contract was done to enhance the collection and evaluation of data on optical properties of various solid state materials. This work included both the development of hardware and software devices for this purpose. Part II of this report describes the hardware and software which was developed to interface a Nicolet 1080 computer to the GPIB (IEEE-488) specifically for use with a video camera with digital output (via the GPIB). Other work in this area has been previously reported on in various quarterly status reports and Technical Memoranda. Briefly, this work consisted of:

- (1) The construction of a data encoder for use with various spectrometers with analog output. This encoder is used with a Sykes Comm-Stor (Communications/Storage) unit to create files of data which are later transferred to the CDC6600 and analyzed using softare created for a Digilab FTS-14 spectrometer (see Final Report RADC-TR-78-61 for details of the FTS-14 software).
- (2) Revision of the FTS-14 data reduction and analysis software for use with various signal sources including the above mentioned encoder. This revised software is used with output from the data encoder, a punched paper tape recorder as well as the FTS-14.

- (3) Investigation into the generation of correlation masks using the AFGL CRT plotter. This included the generation of resolution test strips and corrected resolution test strips based on correction coefficients found from the uncorrected strips. In addition, assembly language programs were developed for the Nicolet computer to test the feasibility of using this device to generate correlation masks in real time.
- (4) A set of software tools for signal processing and display, labeled collectively as SIGPRODS, was modified for use with parametric plots. This is specifically used with software which is used to model the operation of a class of tunable lasers.

#### SECTION I

# Fiber Optic Wavelength Multiplexers

During the duration of this contract we concentrated our efforts on developing new concepts for fiber optic wavelength multiplexers.

In particular we were interested in devices which are easy to fabricate and thus economical and which display low insertion loss. This led us to the idea that one could devise a single element multiplexer. The literature on multiplexers, not a very extensive one, was searched. Basically, multiplexers utilize two elements: a focussing-collimating lens and a dispersive element. The dispersive element can take the form of a prism but preferably a diffraction grating to keep the size of the device small. One can also utilize for channel separation a number of narrow band interference filters arranged in a structure which allows separating the various channels (optical carriers) at different output ports.

The concept of a single-element multiplexer triggered our interest in Fresnel Zone Plates (FZP) because FZP's act as focussing diffraction gratings and have high dispersive power.

The focal length of a FZP is inverse proportional to wavelength. Let the focal length be fg at a wavelength of  $\lambda_g$  at an arbitrary wavelength  $\lambda$ , we have

$$f(\lambda) = f_0 \frac{\lambda_0}{\lambda} \tag{1}$$

Taking the logarithmic derivative of (1), we obtain

$$\frac{\mathrm{d}f}{f} = -\frac{\mathrm{d}\lambda}{\lambda} \tag{2}$$

And thus the axial separation between two adjacent channels is

$$\Delta f = f \frac{|\Delta \lambda|}{\lambda} \tag{3}$$

where  $\Delta\lambda$  is the interchannel separation, typically 20-30nm.

On the question of low insertion loss of the demultiplexer, one must be careful to select the proper type of FZP.

A "black-and-white" FZP consisting of alternative opaque and transparent zones has a maximum efficiency of 10%, that is, it introduces an insertion loss of 10dB.

A phase reversal FZP, in which all zones are transparent but they introduce a differential phase retardation of  $\pi$  between adjacent zones, has a maximum efficiency of 40%, i.e., an insertion loss of 6dB.

One can do better by utilizing a phase Fresnel lens or as it has been recently designated, a blazed Fresnel Zone Plate (BFZP). Such a device is capable of the dispersion given by equations (1)-(3) but introduces negligible insertion loss over a 20% bandwidth.

The real problem that remains to be solved is to find a good method for fabricating a BFZP. Interest in BFZP exists also in the X-ray field where it can be used as an efficient lens. By holographic methods one can create FZP's which are highly efficient in materials such as dichromated gelatin. The problem is that most of the interest in fiber optics is in the near infrared portion of the spectrum where no known materials exist for holography. To circumvent this problem, one can create the FZP's with an argon laser at a visible wavelength, say  $\lambda = \emptyset.515 \mu m$  and playback in the IR. Work remains to be done to reduce the aberrations which occur when a hologram is made at one wavelength and played back at a different wavelength.

A paper on the Fresnel Zone Plate demultiplexers by Haim Haskal has been presented at the Conference on the Physics of Fiber Optics in Chicago on April 28, 1980. The full paper is scheduled to appear in the proceedings of the conference.

#### SECTION II

# Charge Coupled Device Fabrication Steps

#### I. INTRODUCTION

During the contract period my effort has related largely to the preparation and processing of silicon wafers to be used in the fabrication of experimental charge coupled devices (CCD) (1) For the most part this work has involved day to day contact with members of ESE, particularly Mr. Irvin Berman. Periodic written reports (guarterly) and special oral and written reports have been submitted to PML and the Contract Monitor.

Major emphasis has been on the selection and evaluation of wafers, the oxidation of wafers, and the preparation of films of polycrystalline silicon and Silicon Nitride on the oxidized wafers.

Along with the day to day laboratory type activities, literature surveys and evaluations, somehwat in the form of annotated bibliographies, have been made. These studies include:

- a) Limitation imposed on CCD's due to the quality of available silicon wafers.
- b) Problems related to the SiO2/Si interfaces.
- c) Front side and back side lettering techniques.
- d) Expetaxial growth mechanisms for polycrystalline silicons, silicon nitride (Si<sub>3</sub>N<sub>4</sub>) and low temperature silicon dioxide (SiO<sub>2</sub>) layers.
- e) New technology that may impact CCD.

These literature surveys (together with copies of almost all the articles referred to therein) are available in ESE. In this report we are merely summarizing some of the conclusions and/or recommendations that have evolved from the combination of the laboratory activities and the current literature studies. These recommendations and conclusions are specific to the specialized ESE environment where it is desired to make sample quantities of research devices at or beyond the present state of the art. The referneces given in this report are for the most part quite general and are for background to the specific area rather than justification for the conclusions.

## II. LIMITATIONS IMPOSED ON CCD DUE TO THE QUALITY OF THE WAFER USED

- 1. There is little liklihood that any material will replace silicon as the semiconductor from which CCD's are made. Hess and Sah (2) show that the higher mobilities of less tightly bonded semiconductors (e.g., III-V Compounds) cannot be effectively used because of the saturation of the drift velocity of the electrons and the hot electron effects in the fringing fields inherent in the CCD geometry. Jastrzebski (3) shows that deep recombination centers are the limiting crystal defect in silicon CCD devices. These types of defects are far more numberous in compound semiconductors. Hence this report will discuss silicon only.
- 2. Charge Coupled Devices are extremely sensitive to defect introduced both in the silicon growth procedures and in the processing steps applied to the silicon wafers prepared from the grown crystals. Hence the problems for achieving the objectives of Very Large Scale Integration (VLSI) and Very High Speed Integration (VHSI) are closely related to the corresponding problems in CCDS. Specifically, these objectives are higher density of smaller elements on larger chips, higher speed, greater reliability, higher vields and lower costs.
- 3. The rapid progress made in the last few years on the objectives cited above have been largely due to improvements in the processing steps on the wafers. There has been considerable discussion and difference of opinion on whether or not the present quality of crystals grown by the Czochralski or Float Zone technique are adequate to meet the needs of submicrometer size devices. Stated another way, the question is as follows: can improvements (lower temperatures) in the processing steps and gettering and annealing techniques compensate adequately for the defects in the "as grown" crystals?

First we will briefly summarize the crystal growth situations. Practically all of the research and development on production and experimental devices utilize dislocation free Czochralski (CZ) or Float Zone (FZ) crystals. Consequently, we will confine our attention to these forms of silicon crystal growth.

The CZ crystals have the advantages of higher physical perfection, ready availability and better cost and yield factors. The FZ crystals have greater chemical purity but suffer higher levels of physical imperfections. The greater chemical purity of the FZ crystals is due to the elimination of the quartz crucible and carbon susceptors and resistance heaters which are the principal source of oxygen and carbon impurities in the CZ process. The greater physical perfection of the CZ crystals is due to a larger melt in which the thermal convection currents are better controlled. Extensive discussions of the status of CZ and FZ growth, the effects of oxygen and

carbon and the types and nature of crystal defects are given in publications of the Electrochemical Society (4) and the International Conference on Crystal Growth (ICCG) (5). An excellent review of the limitations imposed on the CZ growth by thermal convection effects has been published by J.R. Carruthers (6) and by Carruthers and Witt (7). A similar review emphasizing F2 crystals has been published by deKock (8). These publications and a large number of current papers adequatley attest to the difficulty of improving either of these types of crystal growths (CZ or FZ). A summary of selected properties of single crystal silicon together with the present capabilities and requirements for VLSI is given in Table I which is taken from Bullis (9). This table is originally from a report, as yet unpublished, by a select committee of The National Academy of Science (10). The table clearly shows the need for improvements of a factor of ten or better in many cases. Such improvements are unlikely in the near future in large diameter crystals.

TABLE I
Selected Properties of Single-Crystal Silicon

Property	Current Ca Czochralski	pabilities Float Zone	Requirements for VLSI
Resistivity n-type (P), $\Omega \cdot cm$ Resistivity n-type (Sb), $\Omega \cdot cm$	1-40 0.005-10	1-300	100-400 0.0002-0.02
Resistivity p-type (B), 1.cm	0.005-50	1-300	100-400
Resistivity gradient (four-probe) %	5-10	20	<1
Resistivity microsegregation, %	10-15	20-50	<1
Minority carrier lifetime, s	30-300	50-500	300-1000
Oxygen, ppma	5-15	Not detected	Uniform and controlled
Carbon, ppma	1-5	0.1-1	0.1
Heavy-metal impurities, ppba	1	0.01	0.001

The conclusion from a fairly extensive study of many of these factors is simply that ESE should continue to use wafers of  $\leq 2$  inches in diameter with a strong preference for FZ crystals. The smaller diameters allow much greater crystal perfection due to much better control of convection factors. The FZ crystals, despite larger resistivity striations have much smaller variations in generation lifetime. This is in turn due to the lower level of deep recombination centers made possible by reduction of oxygen and carbon in FZ crystals.

4. Since the number of wafers used in an experimental program is quite small, and the research time spent per wafer is high, the cost per wafer is relatively insignificant. Hence one should acquire the best possible pedigreed wafers to the most exacting specifications.

The incoming wafers should be extensively tested on a sample basis and processed ins small batches of the order of ten at a time. The desirable incoming tests are a) X-ray topography, b) Phase Contrast microscopy on "Secco" etched wafers and c) Capacitance-voltage measurements (C-V). All three of these tests are time consuming and the latter two are destructive as well (i.e., further processing steps would be required before reusing the wafer). Nevertheless, physical tests like (a) and (b) are essential, as well as electrical tests like (c) in order to correlate electrical properties of the experimental devices with physical and chemical properties of the wafer. ESE has excellent capability for all three of these tests.

5. What is really needed is a rapid, non-destructive imaging technique that would put a high resolution image of the defect pattern of a wafer onto a cathode ray tube. The best approach (11), (12) to this type of device is to use laser scanning beams to measure surface and interface properties of wafers before and after various process steps. Distefano's device has been developed with partial support of government funds. Such a piece of measuring equipment would be a great asset to ESE.

Bullis (9) has written an excellent review of methods of characterizing semiconductor material. Another excellent recent review of the present status of silicon for electronic devices is given by Bradshaw and Goorissen (13).

It is strongly recommended that Dr. W. Murray Bullis (National Bureau of Standards) be consulted both on the appropriate wafer tests and on acceptable sources of wafers.

#### III. PROBLEMS RELATING TO SILICON OXIDATION

Having selected and prepared the wafer, the next step is to put onto it a layer of the order of 0.1 to 1.0 micron (1000 to  $10,000~\rm A^{\rm O}$ ) of silicon dioxide ( $S_{\rm i}O_{\rm 2}$ ). The current accepted practice is to use a dry thermal oxidation at a temperature of the order of  $1000{\rm C^{\rm O}}$ . The time and temperature cycle for these oxidations is such that many defects native to the wafer are developed and many more may be introduced in this processing step. Furthermore, the properties of the interface between the silicon and the silicon dioxide layer (Si/SiO<sub>2</sub>) often varied widely. These properties (fixed Oxide Charges Of and Nf) are very important in many CCD devices.

Because of inadequate knowledge of the oxidation mechanism, the physics and chemistry of the Si/SiO2 interface, the effects of thermal annealing on the defect structure and inconsistency in definitions and nomenclature, it was difficult to follow and evaluate much of the copious literature in this area. The situation is now becoming much clearer. The nomenclature and definition problem has been clarified by Deal and his Committee (14). The Si/SiO<sub>2</sub> interface problems are reviewed in a comprehensive way in the Proceedings of the International Conference on the Physics of  $SiO_2$  and Its Interfaces (15). The understanding of the roles of chlorine (16) and hydrogen (17) in frontside gettering has permitted much more consistent data. Backside gettering (18) is a technique wherein purposely introduced imperfections (dislocations) in the inactive portion of the silicon wafer act as sinks to remove imperfections and impurities from the critical active device regions of the wafer. This technique (backside gettering) is probably the largest single advance in device processing introduced in the last several years in terms of increased yield and quality of devices.

The combination of frontside gettering (using chlorine), backside gettering (using phosphorous diffusion) and controlled annealing should allow the processing of excellent SiO<sub>2</sub> layers with superior Si/SiO<sub>2</sub> interfaces onto excellent quality substrates.

The particular implementation of these techniques depends on the circumstances of the particular group involved. The particular recommendations for ESE are as follows:

a) The backside gettering, using the phosphorous diffusion technique of Rozgonyi (18) is preferred. ESE has also the capability for backside gettering by ion implantation and/or mechanical abrading (sand blasting).

b) The frontside gettering technique of Hattori (19), (29) which uses a N2/HC1/O2 preoxidation anneal is preferred. However, Trichlorethylene (TCE)(21) should be used in place of HCl as it is less corrosive and easier to handle. One significant advantage of this preoxidation anneal is that it is done "in situ" immediately prior to the oxidation and acts as a final cleaning step for the wafer. The importance of the proper combination of frontside gettering, backside gettering and slow annealing on the defect structure of Float Zone wafers is clearly shown by Rohatgi and Rai-Choudhury (22). Their technique, which can be readily combined with that of Hattori yields millisecond carrier lifetime measurements which are indicative of very high quality defect free wafers. These combined techniques applied to two inch diameter Float Zoned wafers should provide high quality oxide layers with good interface properties and potentially excellent CCD device properties (low leakage, etc.).

#### IV. DEPOSITION OF POLYSILICON LAYERS

The preparation of thin films of semiconductors onto substrates of identical composition (epitaxy) and onto substrates of different composition (hetero-epitaxy) by Chemical Vapor Deposition (CVD) techniques has increased very rapidly over the past decade and it can easily be predicted that this trend will continue for many years to come. There are several reasons for this situation:

- a) The planar technology has required relatively thin active layers with precisely controlled properties. The drives toward VLSI and VHSI sharply accentuate the importance of thin high guality layers (usually in the region of 100 to  $1000~{\rm A}^{\rm O}$ ).
- b) CVD is an extremely versatile technique with a very wide range of applications for elemental and compound semiconductors, conductors, resistors, and capacitative components.
- c) The cost and complexity of setting up an epitaxial system is far less than to set up a Czochralski or Float zone facility.
- d) There are very many opportunities for practical application investigations as well as fundamental investigations of CVD processes. In other words, the potential field for new research opportunities is much larger and the state of the art is far less developed than that of growth from the melt.
- e) There are very many investigations that are suitable for doctoral theses in universities without excessive investment in capital equipment. The individuals thus trained are highly desirable in small and specialized, as well as large and generalized industrial organizations.
- f) New epitaxial techniques will probably replace many presently used processing steps (see Section V of this report - New Technologies).

There are a number of excellent reviews on the subject of Chemical Vapor Deposition of semiconductors (23) and particularly of silicon (24). Our attention has been confined to the deposition of polysilicon by CVD with emphasis on low pressure CVD (LPCVD) and plasma enhanced CVD (PECVD).

The advantages of LPCVD are clearly spelled out by Hammond (23). He outlines a simplified barrier layer theory in which he shows that the diffusion rates for the gaseous species are inversely proportional to the total system pressure and directly proportional to the partial pressure of the gaseous species in the mainstream. Also the diffusion rate is directly proportional to temperature to the three-halves power  $(T^{3/2})$ . Thus, by reducing pressure from one atmosphere to a fraction of a TORR, the

diffusion rate is increased by a factor of about a thousand while the deposition rate is reduced very little since no dilutent gases are used. Thus, the uniformity of the deposited layers is greatly enhanced, within the individual wafers, from wafer to wafer, and from batch to batch. The merits and details of LPCVD are discussed by Rossler (24), by Ogirima et al (25), and by Spear and Wang (26).

The specific applications of LPCVD for ESE are discussed in an internal report (27). This report discusses two LPCVD systems. One of these is essentially a "turn key" retrofit system to be installed on the ESE Lindberg furnace. The other is an "in house" experimental system which is scaled down for specific needs. Operation of the first system is now scheduled for April 1981. The second system is currently being "debugged".

It is recognized that Plasma Enhanced CVD systems (PECVD) may have many advantages over LPCVD systems. However, they also have additional compilations so that there will be little emphasis in ESE on PECVD until after the LPCVD is fully implemented. It is the present intent to use a system which is a modification of that Rosler and Engle (28). The current thinking concerning the proposed system is discussed in the internal report cited (27). It represents a conversion of the present MiniPak II system to an R.F. Heated Hot Wall system.

# V. NEW TECHNOLOGIES THAT MAY INFLUENCE NEW CCD DEVICES

Some effort has been expended in exploring new technologies that may influence future directions of VLSE, VHSI and CCD research. They will merely be mentioned here. The most significant trend in my opinion is the increasing significance of Chemical Vapor Deposition. A good part of the recent success has related to better control of the variables involved and to higher purity intermediate starting materials such as SiCl<sub>4</sub>, SiHCl<sub>3</sub> and SiH<sub>4</sub>.

The major limitations of CVD has been the substrates. The possibilities of reusing substrates by cleaving the epilayers, the use of contoured foreign substrates (graphoepitary) and the use of laser, electrons and ion beam annealing of epitaxial layer or foreign substrates may radically change our current processing technologies in the next decade. The ability to deposit SiO2 layers by CVD techniques whose properties are comparable or superior to thermal SiO2 is apparently possible (29).

Despite theoretical arguments that ideal  $SiO_2$ -Si interfaces are possible (30), it is unlikely, in my opinion, that the fixed charge density at the  $SiO_2$ /Si interface will be reduced much below the present best values of the order of  $10^{10}\,\mathrm{cm}^{-2}$ . Despite the central importance that  $SiO_2$  has had on the development of

our current electronic devices and systems, it may be necessary to develop a new insulating interface with appropriate crystallographic, as well as thermal and mechanical properties if we are to greatly improve on present interface conditions and to make truly three-dimensional (layered) VLSI and VHSI devices. One possibility would be magnesium Spinel MgAl $_2$ 04 if it could be deposited on silicon substrates in single crystal form by metaloorganic techniques. Then multiple alternate layers of single crystal silicon and spinel could be used to explore the feasibility and desirability of truly three-dimensional devices.

The rapid development of computer aided design and computer aided manufacturing techniques (CAD/CAM) will greatly accelerate new VLSE, VHSI and CCD design and prototype chips at greatly reduced cost.

# VI. FUTURE DIRECTIONS

It is anticipated that next year's efforts will be much more restricted in scope and relate the experimental aspects of the LPCVD and PECVD programs.

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#### SECTION III

# Generation of Short, High-Energy Pulses

During this period, a major effort was directed toward development of a circuit to produce repetitive, short, high-energy optical pulses. The initial design goal was an optical pulse duration of about 10 ns. Given sufficient energy per pulse, an input pulse of this duration will significantly enhance the resolution performance of the Optical Time Domain Reflectometer presently in operation.

The circuit used in this developmental optical pulser employs a charged delay line as the energy storage element, with an n-p-n transistor operating in the avalanche mode as a switch connecting the delay line to a GaAs laser diode. A series of experiments were performed, using both RCD \$632000 series laser diodes and the Laser Diode Laboratories LCDD Peries diodes. The choice of the switching transistor turns and to be critical, so long as the reverse collector-to-base approximation voltage is greater than the 400 to 500 volts needed to approximate the delay line. With this configuration, using a Matricipia 2N5550 transistor and microstrip delay lines of characeet as in impedances between 2 and 10 ohms, 15 ns optical pulses of up to 20 watts beak power at 900 nm can be reliably obtained at rates of 1000 pps.

The experiments described above employed discrete circuit fabrication techniques. Using these techniques, it is possible that optical pulses as short as 5 ns duration could be generated at the desired power levels. The limitation on the use of discrete circuit components results from the effects of distributed inductance throughout the circuit. To obtain a feel for the magnitude of these effects, at a frequency of 170 MHz, a 1-centimeter length of conductor has a reactance of about 10 ohms; to produce 20 watt optical pulses using existing GaAs laser diodes, the driving pulse current approaches 100 amperes. At these current levels, the inductive voltage drop across even a few millimeters of conductor becomes substantial as the rise time of the current driving pulse approaches a few nanoseconds.

The most promising next step appears to be implementation of this circuit in hybrid form. C. Luddington, of ESED in the Solid State Sciences Division, fabricated 0.5 ohm resistors on 0.01 ohm-centimeter, single-crystal silicon wafer material and mounted several of these resistors in headers. Measurements of these encourage the notion that a hybrid circuit, with the switch transistor, current-limiting resistor and the laser diode all mounted in the same header, would greatly reduce distributed inductance in the circuit, hence making possible shorter optical pulses.

#### SECTION IV

# Theory of Optical Time Domain Reflectometry From Perturbed Fibers

We have developed a theory to describe the Optical Time Domain Reflectometry (OTDR) return signals from weak static perturbations in optical waveguides by employing a time-dependent Green's function formulation. The version of this theory that is applicable to two-dimensional planar waveguides has been presented at the American Ceramic Society's 1980 Chicago meeting and will appear in Advances II: Physics of Fiber Optics. It is included as part of this report [1].

Further calculations for the planar waveguide case have been carried out in order to establish qualitative comparison with experiments that have been performed for perturbations consisting of loops [2] of various diameters ranging from 5 to 12 cm. To facilitate the numerical evaluation of the theory, we have carried out the integration of Equation 37 of Ref.1 analytically. This yields an expression for the backscattered Payleigh power, that can be written as:

$$\frac{P^{(t)}_{(t)}R_{AYLEVEN}}{P_{o}} = \alpha_{RAYLEVEN} \cdot \xi \cdot \int_{-\infty}^{\infty} e^{-(t-s'u_{g}^{-1})^{2}/T^{2}}.$$

$$+ (1-R; -T;) \left[\Theta(3'-a)\Theta(a+L-3')e^{-2\alpha_{TOT}}3' - 2\alpha_{iRAD}(3'-a)\right] + (1-R; -T;)^{2}\Theta(3'-(a+L))e^{-2\alpha_{TOT}}3' - 2\alpha_{iRAD}L\right] d_{3'}$$

$$= \alpha_{RAYLEVEN} \cdot \xi \cdot \frac{\sqrt{\pi}}{2} \cdot \tau u_{g} \cdot e^{-t^{2}/T^{2}}$$

$$+ \left[e^{q^{2}T^{2}u_{g}^{2}/4}\left[1 + erf(q\tau u_{g}/2 + au_{g}^{-1}/\tau)\right] + e^{2\alpha_{iRAD}}a + q^{4}u^{2}v_{g}^{2}/4.$$

$$+ \left[erf(q'\tau u_{g}/2 + (a+L)u_{g}^{-1}/\tau) - erf(q'\tau u_{g}/2 + au_{g}^{-1}/\tau)\right] + e^{-2\alpha_{iRAD}}L + q^{2}T^{2}u_{g}^{2}/4.$$

$$+ \left[1 - erf(q\tau u_{g}/2 + (a+L)u_{g}^{-1}/\tau)\right]$$

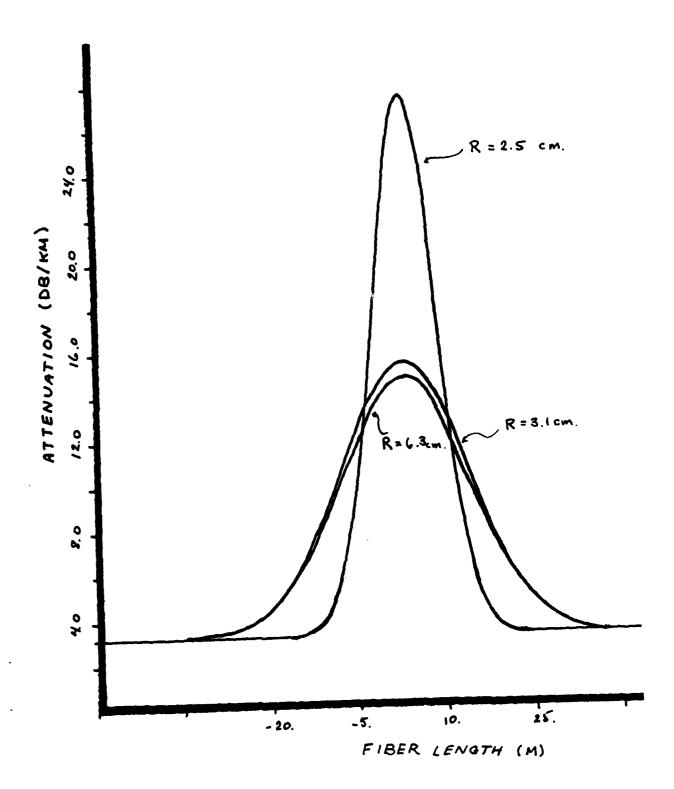


figure 1.

where:

$$g = 2(\alpha_{TOT} - t v_g^{-1}/\tau^2)$$

$$g' = 2(\alpha_{TOT} - t v_g^{-1}/\tau^2 + \alpha_{1RAb})$$

In Figure 1. we have plotted the local attenuation in dB/Km vs. the actual position along the waveguide for loops of various diameters for the parameters of the planar model of Ref.l using the expression for the Rayleigh backscattering power given above in Equation 1.

As mentioned on page 7 of Ref.1, inhomogeneities on a microscopic scale are essentially the mechanism that produces Rayleigh scattering and, for the case of glass fibers, these inhomogeneities are due to thermal fluctuations in density and composition that become frozen in as the glass melt solidifies at temperature Tc. These local fluctuations of density and composition will in turn result in local fluctuations of the refractive index. A calculation of Rayleigh scattering can thus be carried out using the Green's function methods discussed in Ref.1, with the perturbation in refractive index described by

$$\delta n^{2}(\vec{r}) = \left| \frac{\partial n^{2}(\vec{r})}{\partial \rho} \right|_{T_{c}} \Delta \rho(\vec{r})$$
 (2)

where  $\Delta \rho(\vec{r})$  is the fluctuation in density at point  $\vec{r}$  . The scattered field can then be expressed as

$$\begin{split} \delta E_{y}^{\frac{7}{R_{AY}}(\hat{r},t)} &= \sum_{n,i} e^{-(t^{\frac{7}{4}}(3i-3)\nu_{n}^{-i}-3i\nu_{n}^{-i})^{2}/2\tau^{2}} \left(\frac{\omega_{o}^{2}}{2ic^{2}}\right)^{(3)} \\ &\cdot \frac{u_{n}(x)}{\beta_{n}} \left(\frac{-\partial \epsilon}{\partial \rho}\right) \langle o| \Delta \rho_{i} | n \rangle e^{i\omega_{o}t \pm i\beta_{n}} 3^{-i(\beta_{o}\pm\beta_{n})} 3i \end{split}$$

where  $\langle O|\Delta \rho; |n\rangle$  is the matrix element of the density fluctuation

$$\langle 0|\Delta \rho_i|n\rangle = \int_{-\infty}^{\infty} u_o(x) \Delta \rho(x, y_i) u_n(x) dx$$

between the incoming mode  $\iota\iota_\bullet$  and the scattered mode  $\iota\iota_n$  , and i labels the fluctuation volume which is centered around  $z_i$  where

$$z_{i+1} - z_i = h$$

The total back-scattered power relative to the input power will be given by (5)

$$\frac{\delta P_{\text{tot}}^{(-)}}{P_{0}} = \frac{-1}{P_{0}} \frac{1}{2} \int_{-\infty}^{\infty} \left( \delta E_{y \text{ Tot}}^{(-)} \frac{i}{\omega \mu_{0}} \frac{\partial}{\partial 3} \delta E_{y \text{ Tot}}^{(-)*} \right) dx$$

where

$$\delta E_{y \text{ TOT}}^{(-)} = \delta E_{y}^{(-)} + \delta E_{y \text{ PAY}}^{(-)}$$

and the bar indicates a thermal average.

Since

$$\frac{\Delta \rho(3i)}{\Delta \rho(3i) \Delta \rho(3i)} = \delta_{ij} \Delta \rho^{2}$$
(7)

the backscattered power from the extrinsic perturbation and the intrinsic frozen in thermal fluctuations will not interfere and the total backscattered power will be simply the sum of the two component powers. The relative backscattered Rayleigh power can be written as

$$\frac{SP_{RAY}^{(-)}}{P_o} = \frac{1}{4} \left( \frac{\omega_o}{c} \right)^4 \sum_{n=0}^{N} \int_{-\infty}^{\infty} e^{-\left(t - (3'-3) \omega_n^{-1} - 3' \upsilon_o^{-1}\right)^2 / \tau^2}$$

" 
$$\frac{h}{\beta_0\beta_n} \left(\frac{\partial \epsilon}{\partial \beta}\right)_{T_e}^2 \langle 0|\Delta \rho(z')n\rangle \langle n|\Delta \rho(z')|0\rangle dz'$$

(6)

Instead of pursuing a detailed evaluation of this quantity here, we shall obtain an approximate value for it in a rough way to offer a comparison with the formula derived using ray theory [3]. To do this we first approximate all  $\beta_n$  (and  $\nu_n$ ) as being roughly the same and equal to  $\beta_n$  (and  $\nu_n$ ). Having made this approximation, we next assume that enough guided modes exist so that the sum over intermediate states can be approximated by the identity operator. The quantity  $\Delta \rho(z) \Delta \rho(z)$  can then be calculated by thermodynamics [4] to be

$$\overline{\Delta \rho^2} = k T \beta_T \rho^2 / V^*$$

which we further assume to be roughly constant over the guide volume. For purposes of comparison, we take the guide to be planar so that the fluctuation volume can be roughly taken as  $\checkmark$ \*  $\sim ha^2$  with a the guide width. For a multimode step index guide, we approximate  $(\beta,\beta)$  as

$$\frac{1}{\beta_0^2} \sim \frac{n_1^2 - n_2^2}{n_1^2} \frac{a^2}{(\pi/2)^2}$$
 (10)

which then yields a rough upper bound for Rayleigh backscattering in the guide

$$\frac{\delta P^{(-)}}{P_{o}}^{(-)} = \left(\frac{\omega_{o}}{c}\right)^{4} \left(\rho \frac{\partial \epsilon}{\partial \rho}\right)^{2}_{T_{c}} k T \beta_{T} \frac{(n_{i}^{2} - n_{i}^{2})}{\pi^{2} n_{i}^{2}}$$

$$= \int_{0}^{\infty} d3' e^{-(t - (3'-3)v_{n}^{-1} - 3'v_{o}^{-1})^{2}/\tau^{2}}$$

that can be compared with the ray theory formula [3]

$$\frac{\delta P_{env}^{(-)}}{P_{o}} \simeq \left(\frac{\omega_{o}}{c}\right)^{4} \left(\rho \frac{\partial \epsilon}{\partial \rho}\right)_{T_{c}}^{2} k T_{\beta_{T}} \frac{(n_{i}^{2} - n_{i}^{2})}{(6\pi n_{i}^{2})^{2}/2^{2}}$$

$$= \int_{-\infty}^{\infty} d3' e^{-(t - (3' - 3) U_{n}^{-1} - 3' U_{o}^{-1})^{2}/2^{2}}$$
(12)

The Green's function formulation for OTDR in planar waveguides may be extended to the case of circular fiber guides in a straightforward manner. Replacing the eigenfunctions  $u_i(x)$  of the planar guide by  $u_{j,n}(x)$  where l,n designate the angular and radial mode numbers with r the radial coordinate, the Green's function for the circular case may be written as

$$G^{\circ}(\vec{r}, \vec{r}'; \omega) = \frac{i}{2} \sum_{n} \frac{1}{\beta_{n}} u_{n}(\vec{r}') u_{n}(\vec{r}) e^{-i\beta_{n} 1} 3^{-3'} 1^{(13)}$$

where the summation symbol indicates an integral continuum state as well as summation over the bound modes which we abbreviate as  $\hat{N} = \{i, n\}$ . For an initial pulse with a modal content described by the vector  $a_{\hat{n}}$ , i.e.,

$$E(\vec{r},t) = \sum_{\hat{n}} a_{\hat{n}} u_{\hat{n}}(\vec{r}) e^{i\omega_{\hat{n}}t - i\beta_{\hat{n}}} 3^{-(t-t_{\hat{n}})^2/2\tau} N_{\tau}^{(14)}$$

scattering in the backward or forward direction into the  $\hat{\mathbf{k}}^{\text{th}}$  mode will be given by

$$SE_{\hat{k}}^{+}(r,t) = \sum_{\hat{n}} e^{i\omega_{\hat{n}}t - i\beta_{\hat{n}}} 3\left(\frac{\omega_{\hat{n}}^{2}}{2c^{2}}\right) \frac{u_{\hat{k}}(r)}{\beta_{\hat{k}}^{2}} \frac{a_{\hat{n}} \in \hat{n}_{\hat{k}}^{2}}{(\beta_{\hat{n}} - \beta_{\hat{k}}^{2})}$$

$$= \left[f_{\hat{n}\hat{k}} e^{-i(\beta_{\hat{n}} - \beta_{\hat{k}}^{2})a} - g_{\hat{n}\hat{k}} e^{-i(\beta_{\hat{n}} - \beta_{\hat{k}}^{2})(a+L)}\right] N_{z}$$

where

$$\epsilon_{\hat{n}\hat{k}} = 2\pi \int u_{\hat{k}}^*(r) \left[ 8n^i(r) \right] u_{\hat{n}}(r) r dr$$
(16)

and where we have assumed an abrupt transition for the perturbed region starting at z=a and extending to z=a+L. For this case

$$f_{nk} = e^{-\frac{1}{2}(t+(a-3)v_{k}^{-1}-av_{n}^{-1})^{2}/\tau^{2}}$$
(17a)

and

$$g_{nk} = e^{-\frac{1}{2}(t + (a+L-3)v_{k}^{-1} - (a+L)v_{k})^{2}/\tau^{2}}$$
 (17b)

The expressions for transition loss and reflected power are essentially the same as those for the planar case with the set  $\hat{n} = \{1, n\}$  replacing the transverse mode number n in the planar case. As an example, the expression for the power lost due to transition radiation will be given by

$$\frac{8P_{TR}(t)}{P_{o}} = \frac{k_{o}^{2}}{4\beta_{m}} \sum_{\hat{n} \geq \hat{m}} \int d\beta_{n} \frac{1}{P_{k}} \frac{\epsilon_{n\hat{k}} \epsilon_{n\hat{k}}^{2} a_{n\hat{n}} a_{n\hat{m}}^{2}}{(\beta_{n}^{2} - \beta_{n}^{2})(\beta_{n}^{2} - \beta_{n}^{2})}$$

$$\cdot \left\{ \left[ 2 \int_{\hat{n}\hat{k}} f_{n\hat{k}} cos[(\beta_{n}^{2} - \beta_{n}^{2})a] \right] + 2 \int_{\hat{n}\hat{k}} f_{n\hat{k}} cos[(\beta_{n}^{2} - \beta_{n}^{2})(a+L)] \right\}$$

$$- 2 \int_{\hat{n}\hat{k}} g_{n\hat{k}} cos[(\beta_{n}^{2} - \beta_{n}^{2})a - (\beta_{n}^{2} - \beta_{n}^{2})(a+L)] \right\}$$

$$- 2 \int_{\hat{n}\hat{k}} g_{n\hat{k}} cos[(\beta_{n}^{2} - \beta_{n}^{2})a - (\beta_{n}^{2} - \beta_{n}^{2})(a+L)] \right]$$

$$\cdot \left[ 1 - \delta_{n\hat{m}} \right] + \left[ \int_{\hat{n}\hat{k}} f_{n\hat{k}} e^{2a\hat{k}} e^{2a\hat{k}$$

The transverse eigenfunctions for the step index circular guide are more complex than those for the planar guide, with Bessel functions replacing simple exponentials  $^{\{5\}}$ . For the case of the bend perturbation, the double sum in the expressions for scattered power can be simplified due to the selection rule

$$\int_{\infty}^{\infty} \int_{0}^{2\pi} u_{jn}(r) \cos(jq) \left[ r \cos(jq) \right] u_{jm} \cos(jq) r dr dq$$

$$= \frac{\pi}{2} \delta_{l \pm l' \pm 1} \int_{0}^{\infty} u_{jn}(r) u_{jm}(r) r^{2} dr$$
(19)

which allows transitions only to final states  ${\bf l}'$  that differ from the initial state  ${\bf l}$  by one unit of the angular mode number.

The radial portion of the transverse matrix element may be evaluated by reexpressing the integrals involving products of Bessel functions as

$$\int_{A+1}^{a} (xr) J_{\lambda}(x'r) r^{2} dr$$

$$= \left(\frac{1}{x} - \frac{3}{3x}\right) \int_{a}^{a} J_{\lambda}(xr) J_{\lambda}(x'r) r dr$$

$$= \left(\frac{1}{x} - \frac{3}{3x}\right) \left\{\frac{a}{x^{2} - x'^{2}} \left[x J_{\lambda+1}(xa) J_{\lambda}(x'a) - x' J_{\lambda}(xa) J_{\lambda+1}(xa)\right]\right\}$$

with similar expressions for the products of the other Bessel functions. The complete list of integrals needed for the calculation of  $\epsilon_{\hat{\mathbf{A}}\hat{\mathbf{k}}}$  for the case of bends is given in Appendix A.

The only other remaining difference between the circular and planar calculation for OTDR from bends comes from the expression for radiation loss due to tunneling. For the circular case, this is given by [6]

$$\alpha_{J,n\,RAD} = \frac{\sqrt{\pi} \, \varkappa_{\hat{n}}^{\epsilon} \, e^{\left[-\frac{2}{3} \left(\gamma_{\hat{n}}^{3} / \beta_{\hat{n}}^{2}\right) R\right]}}{e_{J} \, V^{\epsilon} \, \gamma_{\hat{n}}^{3/2} \, R^{1/2} \, K_{J-1}(\gamma_{\hat{n}}^{2} \alpha) K_{J+1}(\gamma_{\hat{n}}^{2} \alpha)}$$
(21)

which has the same exponential dependence upon the bend radius  $^{R}$  as does the two-dimensional case plus an additional factor  $^{R1/2}$  in the denominator.

A computer code to evaluate OTDR returns from bends in circular fibers has been prepared and is in the process of being debugged.

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#### APPENDIX A

The integrals needed to evaluate the transverse matrix element for the case of bends in a step index fiber are tabulated below:

(A1) 
$$\int_{0}^{a} r^{2} J_{\nu+1}(xr) J_{\nu}(\sigma r) dr =$$

$$= \frac{a}{(x^{2}-\sigma^{2})} \left\{ 2\nu \cdot J_{\nu+1}(xa) J_{\nu}(\sigma a) - a \left(\sigma J_{\nu+1}(xa) J_{\nu+1}(\sigma a) + x J_{\nu}(xa) J_{\nu}(\sigma a) \right\} + \frac{2ax}{(x^{2}-\sigma^{2})^{2}} \left\{ x J_{\nu+1}(xa) J_{\nu}(\sigma a) - \sigma J_{\nu}(xa) J_{\nu+1}(\sigma a) \right\}$$
(A2) 
$$\int_{a}^{\infty} r^{2} H_{\nu+1}^{(1)}(ixr) H_{\nu}^{(1)}(\rho r) dr =$$

$$= \frac{a}{(Y^{2}+\rho^{2})} \left\{ 2\nu H_{\nu+1}^{(1)}(ixa) H_{\nu}^{(1)}(\rho a) - \rho a H_{\nu}^{(1)}(ixa) H_{\nu}^{(1)}(\rho a) \right\}$$

$$- \rho a H_{\nu+1}^{(1)}(ixa) H_{\nu+1}^{(1)}(\rho a)$$

$$+ \frac{a}{(Y^{2}+\rho^{1})^{2}} \left\{ Y H_{\nu+1}^{(1)}(ixa) H_{\nu+1}^{(1)}(\rho a) \right\}$$

$$+ i \rho H_{\nu}^{(1)}(ixa) H_{\nu+1}^{(1)}(\rho a) \right\}$$

(A3) 
$$\int_{\sigma}^{\sigma^{2}} J_{\nu}(\kappa r) J_{\nu-1}(\sigma r) dr =$$

$$= \frac{a}{(\kappa^{2} - \sigma^{2})} \left\{ 2(\nu - 1) J_{\nu}(\kappa a) J_{\nu-1}(\sigma a) - a\kappa J_{\nu-1}(\kappa a) J_{\nu-1}(\sigma a) - a\sigma J_{\nu}(\kappa a) J_{\nu}(\sigma a) \right\}$$

$$= a\sigma J_{\nu}(\kappa a) J_{\nu}(\sigma a) \left\{ \kappa J_{\nu}(\kappa a) J_{\nu-1}(\sigma a) - \sigma J_{\nu-1}(\kappa a) J_{\nu}(\sigma a) \right\}$$

$$+ \frac{2a\kappa}{(\kappa^{2} - \sigma^{2})^{2}} \left\{ \kappa J_{\nu}(\kappa a) J_{\nu-1}(\sigma a) - \sigma J_{\nu-1}(\kappa a) J_{\nu}(\sigma a) \right\}$$

(A1) 
$$\int_{a}^{\infty} r^{2} H_{\nu}^{(1)}(irr)H_{\nu-1}^{(1)}(\rho r) dr =$$

$$= \frac{a}{(Y^{2}+\rho^{2})} \left\{ 2(\nu-1) H_{\nu}^{(1)}(ira) H_{\nu-1}^{(1)}(\rho a) - i \forall a H_{\nu-1}^{(1)}(ira) H_{\nu-1}^{(1)}(\rho a) - \rho a H_{\nu}^{(1)}(ira) H_{\nu}^{(1)}(\rho a) \right\}$$

$$+ \frac{2aY}{(Y^{2}+\rho^{2})^{2}} \left\{ Y H_{\nu}^{(1)}(ira) H_{\nu-1}^{(1)}(\rho a) + i \rho H_{\nu-1}^{(1)}(ira) H_{\nu}^{(1)}(\rho a) \right\}$$

Using these results, the transverse matrix element for bound to continuum transitions may be expressed (writing N for  $N_{\nu,i}$ ) as

$$(A5) \int_{0}^{\infty} u_{J+1} (x_{J+1}r) u_{J}(kr) r^{3} dr =$$

$$= A_{J+1} B_{J} \int_{0}^{\Delta} J_{J+1}(x_{J+1}r) J_{J}(\sigma r) r^{3} dr$$

$$+ \int_{0}^{\infty} \frac{J_{J+1}(x_{J+1}a)}{H_{J+1}^{(1)}(i y_{J+1}a)} H_{J+1}^{(1)}(i y_{J+1}r) \left[ C H_{J}^{(1)}(\rho r) + C D H_{J}^{(2)}(\rho r) \right] r^{2} dr$$

$$= \left[ \frac{4 (\mu_{O}/\epsilon_{O})^{V_{L}} y_{J+1}^{2} P}{\epsilon_{J+1} \pi a^{2} n (n_{L}^{L} n_{L}^{L}) k_{O}^{2}} \frac{1}{|J_{J}(x_{J+1}a) J_{J+1}(x_{J+1}a)|} \right]^{V_{L}}$$

$$= \left[ \frac{(\mu_{O}/\epsilon_{O})^{V_{L}} y_{J+1}^{2} P}{\epsilon_{J+1} \pi a^{2} n (n_{L}^{L} n_{L}^{L}) k_{O}^{2}} \frac{1}{|J_{J}(x_{J+1}a) J_{J+1}(x_{J+1}a) J_{J+1}(x_{J+1}a)} \right]^{V_{L}}$$

$$= \left[ \frac{(\mu_{O}/\epsilon_{O})^{V_{L}} y_{J+1}^{2} P}{\epsilon_{J+1} \pi a^{2} n (n_{L}^{L} n_{L}^{L}) k_{O}^{2}} \frac{1}{|J_{J}(x_{J+1}a) J_{J}(\sigma a) H_{J}^{(1)}(\rho a)|} \right]^{V_{L}}$$

$$= \left[ \frac{(\mu_{O}/\epsilon_{O})^{V_{L}} y_{J}^{2} (x_{J+1}a) J_{J}(\sigma a) H_{J}^{(1)}(\rho a) - \rho J_{J}(\sigma a) H_{J}^{(1)}(\rho a)}{\epsilon_{J+1} \pi a^{2} n (n_{J+1}^{L}(x_{J+1}a) J_{J+1}(x_{J+1}a) J_{J}(\sigma a) + M_{J+1} J_{J}(x_{J+1}a) J_{J}(\sigma a) J_{J+1}(\sigma a)} \right]^{V_{L}}$$

$$= \left[ \frac{aJ_{J+1}(M_{J+1}a)}{(M_{J+1}a)^{2}} \left[ (y_{J}^{L}+\rho^{L}) (\sigma a) + M_{J+1} J_{J}(x_{J+1}a) J_{J}(\sigma a) J_{J+1}(\sigma a) \right]^{V_{L}} \right]^{V_{L}}$$

$$+ \frac{aJ_{J+1}(M_{J+1}a)}{k_{J+1}(M_{J+1}a)} \left[ (y_{J}^{L}+\rho^{L}) (\sigma a) + M_{J+1}(\sigma a$$

(A6) 
$$\int_{0}^{\infty} u_{y-1}(x_{y-1}r) u_{y}(kr) r^{s} dr =$$

$$= A_{y-1} B_{y} \left\{ \int_{0}^{a} J_{y-1}(x_{y-1}r) J_{y}(\sigma r) r^{s} dr \right\}$$

$$+ \int_{\alpha}^{\infty} \frac{J_{y-1}(x_{y-1}a)}{H_{y-1}^{(1)}(ix_{y-1}a)} H_{y-1}^{(1)}(ix_{y-1}r) \left[ C H_{y}^{(1)}(\rho r) + CD H_{y}^{(2)}(\rho r) \right] r^{s} dr$$

$$= \left[ \frac{4 \left( \mu_{0}/e_{0} \right)^{1/2} Y_{y-1}^{2} P}{e_{y-1} \pi a^{2} n \left( n_{1}^{-1} - n_{2}^{2} \right) k_{0}^{2} 1 J_{y-2}(x_{y-1}a) J_{y}(x_{y-1}a) 1 \right]^{1/2}$$

$$\times \left[ \frac{\left( \mu_{0}/e_{0} \right)^{1/2} \left( 8 \rho P \right)^{1/2}}{\left( e_{y} n \right)^{1/2} a \pi^{3/2} 1 \sigma J_{y-1}(\sigma a) H_{y}^{(1)}(\rho a) - \rho J_{y}(\sigma a) H_{y-1}^{(1)}(\rho a) \right]$$

$$+ \left[ \frac{-a}{(x_{y-1}^{2} - \sigma^{2})} \left[ 2 \left( y-1 \right) J_{y-1}(x_{y-1}a) J_{y}(\sigma a) \right]$$

$$- a \left( x_{y-1} J_{y}(x_{y-1}a) J_{y}(\sigma a) + \sigma J_{y-1}(x_{y-1}a) J_{y-1}(\sigma a) \right) \right]$$

$$+ \frac{2a\sigma}{\left( x_{y-1}^{2} - \sigma^{2} \right)^{2}} \left[ \sigma J_{y-1}(x_{y-1}a) J_{y}(\sigma a) - x_{y-1} J_{y}(x_{y-1}a) J_{y}(\sigma a) \right]$$

$$+ \frac{2a\sigma}{\left( x_{y-1}^{2} - \sigma^{2} \right)^{2}} \left[ \sigma J_{y-1}(x_{y-1}a) J_{y}(\sigma a) - x_{y-1} J_{y}(x_{y-1}a) J_{y}(\sigma a) \right]$$

$$+ \frac{2\sigma}{\left( x_{y-1}^{2} - \sigma^{2} \right)^{2}} \left[ \sigma J_{y-1}(x_{y-1}a) J_{y}(\sigma a) - \sigma a J_{y+1}(\sigma a) \right]$$

$$+ \frac{2\sigma}{\left( x_{y-1}^{2} - \sigma^{2} \right)^{2}} \left[ \left( x_{y-1}^{2} + \rho^{2} \right) \left( \left( 2J_{y}(\sigma a) - \sigma a J_{y+1}(\sigma a) \right) \right)$$

$$+ \left( x_{y-1}^{2} \left( x_{y-1}a \right) + x_{y-1} a K_{y} \left( x_{y-1}a \right) J_{y}(\sigma a) \right)$$

$$+ \left( x_{y-1}^{2} \left( x_{y-1}a \right) + x_{y-1} a K_{y} \left( x_{y-1}a \right) J_{y}(\sigma a) \right)$$

$$- 2\rho^{2} K_{y-1}(x_{y-1}a) J_{y}(\sigma a) + 2 J_{y-1} \sigma J_{y-1}(\sigma a) K_{y} \left( x_{y-1}a \right) \right]$$

### ATTACHMENT A

### FRESNEL ZONE PLATES FOR WAVELENGTH DEMULTIPLEXING

bу

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An analysis is presented on the application of Fresnel zone plates to wavelength demultiplexing in fiber optic systems. A demultiplexer consisting of an off-axis Fresnel zone plate acts as a focusing spectrometer. Blazed Fresnel zone plates have high efficiency over a 20% bandwidth and can demultiplex a large number of channels.

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## INTRODUCTION

Present day optical fibers have capacities which exceed by far the bandwidths required to transmit high speed modulated light signals. To increase the bandwidth utilization of the fiber several light carriers can be simultaneously transmitted - multiplexed - over the same fiber and separated by wavelength - demultiplexed - at the receiving end. The first proponent of wavelength multiplexing was Tomlinson at Bell Telephone Laboratories who analyzed  $^{(1)}$  in detail the requirements and techniques for optical multiplexing. Optical demultiplexers based on blazed diffraction gratings were demonstrated by Tomlinson,  $^{(2)}$ ,  $^{(3)}$  and Aoyama  $^{(4)}$ . Other types of demultiplexers based on interference filters  $^{(5)}$ , prisms  $^{(6)}$ , and aberration corrected concave gratings  $^{(7)}$  were also demonstrated.

In this paper we analyze the performance of a wavelength demultiplexer based on a Fresnel zone plate. The zone plate performs simultaneously the functions of wavelength dispersion and focusing.

### FRESNEL ZONE PLATE THEORY

Fresnel zone plates (FZP) have been used as lenses and as spectrometers in various regions of the electromagnetic spectrum. An excellent article reviewing the properties of FZP was published by  $Young^{(8)}$ . The usual type FZP consists of a series of alternating opaque and transparent annular zones. This FZP is characterized by a transmission function (for an infinite plate)

$$t(r) = \frac{1}{2} + \frac{1}{2} \operatorname{sgn} \left(\cos \frac{kr^2}{2f}\right)$$
 (1)

where <u>r</u> is the radial coordinate in the FZP plane,  $\underline{k} = 2\pi/\lambda$ ,  $\underline{\lambda}$  is the wavelength,  $\underline{f}$  the focal length.

For a normally incident unit plane wave the transmitted electric field can be expanded in a Fourier series

$$E(z,r) = \exp(-jkz) \sum_{n=-\infty}^{\infty} \frac{\sin \frac{n\pi}{2}}{n\pi} \exp(j \frac{nkr^2}{2f})$$
 (2)

In Eq. (2) the terms with n negative represent spherical waves converging toward real foci of coordinates  $(0, \frac{f}{|n|})$ . Similarly the terms with n positive represents spherical waves diverging from virtual foci located at coordinates  $(0, \frac{f}{|n|})$  as shown in Fig. 1. The fraction of the incident light diverted to the first real focus is called the efficiency of the FZP and in this case is given by

$$\eta = \frac{1}{\pi^2} \approx 10\%.$$

A more efficient zone plate can be constructed by replacing the opaque zones, which obstruct 50% of the incident light, by transparent zones which introduce a half wave retardation between adjacent zones as shown in Fig. 2. Such a zone plate is called a phase reversal zone plate and is also characterized by multiple foci but has an efficiency n given by

$$\eta = \frac{4}{\pi^2} \approx 40\%.$$

The focal length  $\underline{f}$  for both types of Fresnel zone plates mentioned above can be related to the zone number  $\underline{m}$  and the radius of the  $\underline{m}^{th}$  zone by

$$f = \frac{r_m^2}{m\lambda} \tag{3}$$

Let the focal length of the FZP be  $\frac{f_0}{0}$  at a wavelength  $\frac{\lambda}{0}$  then at an arbitrary wavelength  $\underline{\lambda}$  we have

$$f(\lambda) = f_0 \frac{\lambda_0}{\lambda} \tag{4}$$

Equation (4) puts in evidence the high dispersion of FZP's which can be used advantageosuly in wavelength demultiplexing.

To improve the efficiency of the FZP beyond the 40% that is possible with the phase reversal zone plate one can use the phase Fresnel lens concept introduced by Miyamoto  $^{(9)}$  in 1961. Instead of introducing an abrupt phase retardation of  $\lambda/2$  at the edge of a zone as in the phase reversal zone plate, in Miyamoto's phase Fresnel lens one introduces a gradual phase retardation over a zone, according to some profile, from zero  $\lambda$  a maximum of  $\lambda$ . The

adjacent zone starts again from a zero phase retardation which is indistinguishable from the  $\underline{\lambda}$  retardation at the edge of the previous zone. In this way the phase retardation appears continuous for the incident light even though the actual phase plate has a dentelated profile. The procedure of constructing a phase Fresnel lens corresponding to a plano-convex lens is illustrated in Fig. 3.

The phase Fresnel lens, also referred to as the blazed Fresnel zone plate (BFZP), as designed in Fig. 3 will focus a plane wavefront at the design wavelength  $\lambda_0$  to a single focus just like the original lens. However, if the wavelength is changed from  $\lambda_0$  to  $\lambda$  some of the light is focused to higher order foci. We will now examine the effect of changing the wavelength on the efficiency of the BFZP.

Let the BFZP introduce a quadratic wavefront deformation given by the phase function

$$\Phi (u,v) = -(u^2 + v^2)/2f_0$$
 (5)

where <u>u</u> and <u>v</u> are transverse coordinates in the plane of the plate and  $f_0$  its focal length at the wavelength  $\lambda_0$ .

The phase transformation, similar to that produced by a thin lens, is characterized by a transmission function (over each zone)

$$t(u,v) = \exp\left[-j\frac{k}{2f_0}(u^2+v^2)\right]$$
 (6)

The focal length of the BFZP obeys the relation given by Eq. (4). At an arbitrary wavelength the transmission function can be expanded (over each zone) as

$$\exp (-j2\pi\Phi/\lambda) = \sum_{\ell=-\infty}^{\infty} A_{\ell} \exp(-j2\pi\ell!/\lambda)$$
 (7)

where

$$\phi(u,v) = \frac{\lambda}{\lambda_D} + (u,v)$$

Substituting for the coefficients  $A_{ij}$  in eq. (7) we obtain

$$\exp(-j2\pi\phi/\lambda) = \frac{\sin \pi(\lambda_0 - \lambda)/\lambda}{\pi(\lambda_0 - \lambda)/\lambda} \exp \{-j2\pi\theta/\lambda - j\pi(\lambda_0 - \lambda)/\lambda\}$$

$$x \left[ 1 + \frac{\lambda_0^{-\lambda}}{\lambda_0} \exp(j2\pi\theta/\lambda) + \frac{\lambda_0^{-\lambda}}{\lambda_0^{-2\lambda}} \exp(-j2\pi\theta/\lambda) + \dots \right].$$
 (8)

At the design wavelength  $\lambda_0$  only the first term in the series survives corresponding to a single real focus. As one deviates from  $\lambda_0$  higher order foci appear. To estimate the fraction of energy diffracted at the first real focus, i.e. the efficiency  $\eta$ , as a function of wavelength, we consider the coefficient of the first term in Eq.(8). The efficiency is given by

$$\eta = \left[ \frac{\sin \frac{\pi \Delta \lambda}{\lambda_0} \left( 1 + \frac{\Delta \lambda}{\lambda_0} \right)}{\frac{\pi \Delta \lambda}{\lambda_0} \left( 1 + \frac{\Delta \lambda}{\lambda_0} \right)} \right]^2$$
 (9)

where  $\Delta\lambda$  is the deviation from the design wavelength  $\lambda_0$ . If we set  $\Delta\lambda/\lambda_0$  =  $\pm$  10% in Eq. (9)we obtain the value 0.96; thus only 4% of the energy is diffracted into the zero and higher order foci. A BFZP can therefore be an efficient demultiplexer with 20% bandwidth. Such a bandwidth can accommodate 10 optical channels 20 nm apart around a center wavelength  $\lambda_0$  = 1.0  $\mu$ m.

## THE USE OF THE BFZP FOR WAVELENGTH DEMULTIPLEXING

The BFZP can be used in several configurations (reflection, transmission) as a dispersive and focusing device for wavelength demultiplexing. It has, in fact, been proposed for use as a focusing spectrometer at soft x-ray wavelengths (10). One cannot use a full BFZP for demultiplexing because the images of the input fiber at the various wavelengths appear along the axis one in the shadow of the other. If an array of detectors is placed at the image positions, the first detector will obstruct some of the light meant to reach the others, in addition crosstalk between channels will be very high. To alleviate this problem one can use an off-axis BFZP; light is now focused towards the various images only from one side of the plate and the array of channel detectors can be placed along the BFZP axis or at an angle to the axis without interference.

We illustrate the use of a BFZP in an off-axis configuration in Fig. 4. The light emanating from a multimode optical fiber is collimated prior to entering the BFZP. Two adjacent optical channels at  $\lambda_0$  and  $\lambda_0 + \Delta\lambda$  are focused at  $F_1$  and  $F_2$ . The separation between the two channels along the axis can be obtained from Eq. 4 and is given by

$$\Delta f = f \frac{|\Delta \lambda|}{\lambda_c} \tag{10}$$

where  $\Delta\lambda$  is the wavelength separation between the channels. From Eq. (10) one determines the size of photodetectors as a function of the BFZP focal length and wavelength. The light impinges on the detectors located along the axis at a very shallow angle, close to grazing incidence and therefore the reflection loss can be considerable. It is, therefore, necessary to coat the photodetectors with antireflection coating suitable for that angle of incidence.

We have shown in Fig. 5 a two-channel demultiplexer with the detectors inclined at an angle  $\delta$  to the BFZP axis; they are located such as to intercept all the light from the respective image of the fiber.

The angle  $\delta$  is determined from the geometry

$$\tan \delta = \frac{r_m - D + \epsilon a}{f} \tag{11}$$

where  $r_m$  is the radius of the  $\underline{m}^{th}$  zone of the BFZP,  $\underline{D}$  is the diameter of the collimated beam,  $\underline{\varepsilon}$  is the angle of divergence of the collimated beam,  $\underline{a}$  is the distance between the collimating lens and the BFZP.

We also have the following relations

$$D = 2(NA) f_{col}$$
 (12)

where (NA) is the numerical aperture of the fiber,  $f_{col}$  the focal length of the collimating lens.

$$\varepsilon = \frac{f}{f_{col}} d_{core}$$
 (13)

where  $\mathbf{d}_{\text{core}}$  is the core diameter of the fiber.

From Eq.(3)we obtain the relation

$$\frac{f}{r_{\rm m}} = \frac{\Lambda r}{\lambda} \tag{14}$$

where  $\underline{r}$  is the width of the  $\underline{m}^{th}$  zone. Substituting into Eq. (11) we obtain

$$\tan \delta = \frac{\lambda}{\Delta r} - 2(NA) \frac{f_{col}}{f}$$
 (15)

where we have assumed that the term  $\epsilon a$  in Eq. (11) is negligible. If one uses a unity magnification imaging system  $\frac{f_{col}}{f}$  = 1; NA = 0.2,  $\lambda$  = 1  $\mu m$  and  $\Delta r$  = 1  $\mu m$  we obtain

$$\tan \delta = 0.6$$
 ...  $\delta = 30.96^{\circ}$ 

Thus in this case the antireflection coating for the photodetector must be designed for light incident at  $59^0$  with respect to the normal if the detector is placed along the axis of the BFZP. If the detectors are inclined at angle  $\delta$  with respect to the axis the antireflection coating should be designed for an incidence angle of  $28^0$  with respect to the normal to the photodetector.

The dimensions of the BFZP need not be very large and are compatible with fiber optic systems. If we choose  $f=f_{\text{Col}}=6$  mm , $\lambda=1$   $\mu\text{m}$  ,  $\Delta r=1$   $\mu\text{m}$ , the diameter of the collimated beam equal to the off-axis BFZP diameter is

$$D = 2 (NA)f_{CO1} = 2.4 mm$$

The number of zones which must be ruled is readily computed to be 1920.

# FABRICATION CONSIDERATIONS

To fabricate a blazed Fresnel zone plate several avenues are open:

- a) <u>Diamond point turning</u>. Considerable progress has been reported in the last few years in the design and implementation of computer controlled diamond turning machines. Such machines are capable of generating the required phase profile in soft plastic materials to produce a BFZP.
- b) <u>Computer generated phase profiles</u>. It has been shown about a decade ago that a computer generated phase hologram, labelled a kinoform, is entirely equivalent to a phase Fresnel lens. A good bibliography on this subject is found in Clair and Abitbol<sup>(11)</sup>.

c) Holographic generation. Instead of producing a relief pattern one can induce a change in the refractive index of certain materials by exposure to light and realize a Fresnel zone plate. Opterating near the Bragg angle such a Fresnel plate has high dispersion and focusing power just like the BFZP. Recent advances in the fabrication of dichromated gelatin have resulted in very large index changes in the material under exposure to light. This makes dichromated gelatin an attractive material for infrared applications. Some problems still remain to be solved because the material must be exposed with visible light (for maximum sensitivity) and used with infrared light for fiber optic systems. Such a wavelength shift between construction and reconstruction introduces severe aberrations.

### CONCLUSIONS

An off-axis BFZP constitutes an attractive candidate for a multichannel near infrared fiber optic demultiplexer. More research must be devoted to devise methods of producing a BFZP.

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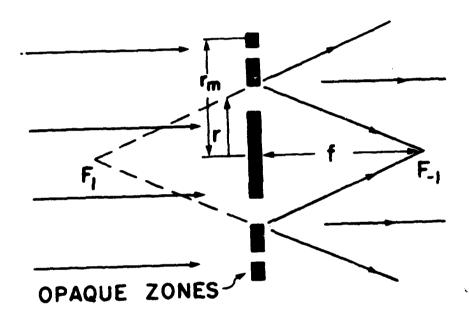


Fig. 1 Fresnel zone plate

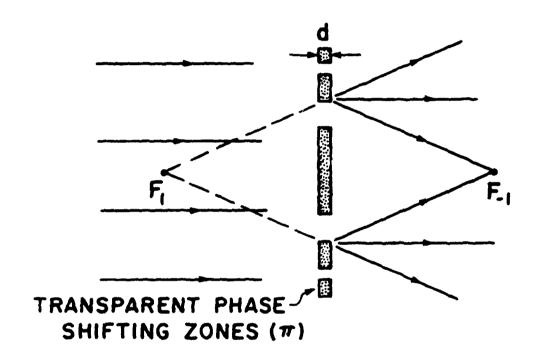


Fig. 2 Phase reversal Fresnel zone plate  $d = \frac{\lambda}{2(n-1)}$ , n is the refractive index.

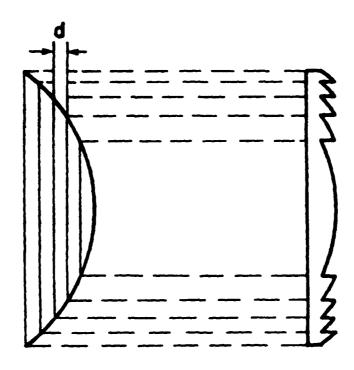


Fig. 3 Blazed Fresnel zone plate construction equivalent to spherical lens d =  $\frac{\lambda}{n-1}$ 

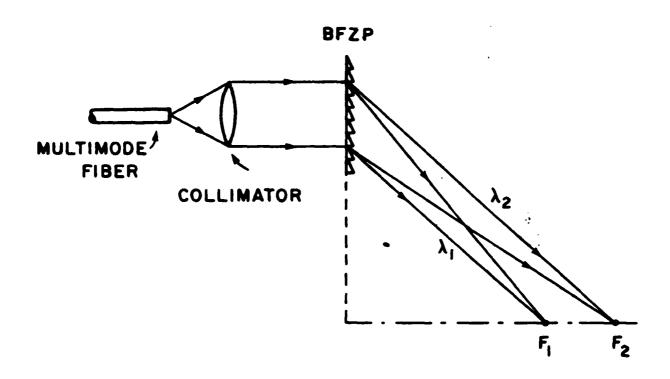


Fig. 4 Off-axis BFZP demultiplexer.

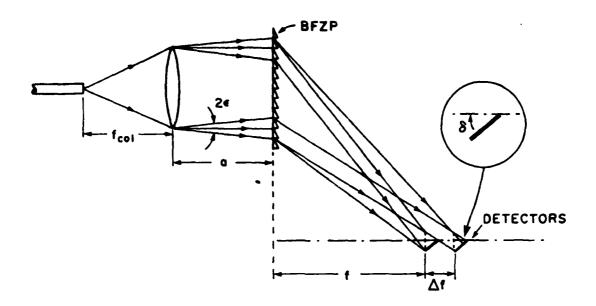


Fig. 5 2-channel 8FZP demultiplexer with detectors.

### ATTACHMENT B

# THEORY OF OPTICAL TIME DOMAIN REFLECTOMETRY FROM PERTURBED FIBERS

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## **ABSTRACT**

We formulate a theory of backscattering from static perturbations in fibers, and apply the results to predict the OTDR signal for perturbations such as bends. A variety of effects are examined in detail, such as transition loss, curvature loss, dependence on mode number and dependence on pulsewidth.

<sup>\*</sup>Research supported by Solid State Sciences Division, RADC(AFSC) under contract No. F19628-78-C-0089.

### I. INTRODUCTION

In optical time-domain reflectometry (OTDR), optical pulses are launched into a fiber waveguide and the back-scattered signal is measured as a function of time <sup>1</sup>. For a uniform unperturbed fiber the OTDR signal consists entirely of Rayleigh back-scattering, and displays an exponential decrease as a function of time due to the absorptive and scattering losses of the fiber. In this work we examine backscattering from static perturbations (slowly varying compared to the pulse width) in optical waveguides. The exponentially decreasing OTDR intensity will in this case be modified due to reflections and radiation losses induced by the perturbation. Corresponding changes will also occur of course in the spatial and temporal makeup of the pulse although we do not consider these here.

In order to calculate the OTDR return, we employ a time-dependent Green's function (GF) method. Although the equations derived in this way are intractable in general, it is possible to obtain explicit but approximate expressions for the case of weakly perturbed fibers by approximating the exact GF's by their unperturbed counterparts. One fortunate consequence of the lowest order theory is that the contributions to the OTDR intensity from random scattering processes (i.e., Rayleigh scattering) and from deterministic perturbations do not interfere.

The detailed properties of the backscattered signal depend, of course, on the specific form of the perturbation and the characteristics of the wave-guide. Nevertheless, certain general features emerge from the present formulation as illustrated by the specific example of bend perturbations. For example, when a uniformly perturbed region is involved, then the net scattering from the interior of the perturbed region vanishes, leaving contributions from just the ends. In higher order, modes may mix in the interior and tunnel cut of the guide as well. In general both reflections and transition losses will be manifested in the OTDR signal, with the characteristics of this signal depending on the symmetry of the perturbation. For example, for a single mode waveguide reflection will be totally absent in lowest order if the perturbation possesses odd symmetry, but is present for even symmetry. Transition losses, on the other hand, will occur in either instance. We perform a variety of computations to illustrate the dependence of OTDR from bends on launch

conditions, pulsewidth, bend length, and bend radius.

## II. GREEN'S FUNCTION THEORY FOR PROPAGATION IN PERTURBED WAVEGUIDES

In this section we utilize time-dependent GF theory to obtain an expression for the change in the time-dependent field amplitude in a fiber induced by a perturbation. The results will be used in subsequent sections to evaluate the OTDR return from fiber bends.

For the case of fiber waveguides for which the difference between core and cladding refractive indices is small, which includes the majority of waveguides of interest, the vector wave equation for the waveguide modes may be approximated by equivalent scalar equations for TE and TM modes. Taking z as the propagation direction and assuming solutions of the form

$$\vec{E}(x,y,z,t) = \vec{E}(x,y) e^{i\omega t - i\beta z}, \qquad (1)$$

the wave equation for TE modes may be written as

$$\left\{\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \left(\frac{\omega^2}{c^2} n^2(x,y,z) - \beta^2\right)\right\} E_y(x,y) = 0.$$
 (2)

For simplicity we first consider the case of planar waveguides. In this instance we have

$$n^{2}(\vec{r}) = n^{2}(x,z) = n_{0}^{2}(x) + \delta n^{2}(x,z)$$
 (3)

where  $n_0^{\ 2}(x)$  represents the unperturbed guide and  $\ \delta n^2(x,z)$  the perturbation.

Eigensolutions for the unperturbed guide

$$\left\{ \frac{\partial^2}{\partial x^2} + \left( \frac{\omega^2}{c^2} n_0^2(x) - \beta_n^2 \right) \right\} u_n(x) = 0$$
 (4)

can be used to construct the GF for the unperturbed guide as  $^2$ 

$$G^{0}(\vec{r},\vec{r};\omega) = \frac{1}{2\pi} \sum_{n} \int \frac{u_{n}^{*}(x')u_{n}(x)e^{-i\Lambda(z-z')}}{\beta_{n}^{2} - \Lambda^{2}} d\Lambda$$

$$+\frac{1}{2\pi}\int d\beta_k \int \frac{u_k^*(x')u_k(x)e^{-i\Lambda(z-z')}}{\beta_k^2 - \Lambda^2} d\Lambda$$
 (5)

which can, by contour integration, be reduced to

$$G^{0}(\overrightarrow{r},\overrightarrow{r}';\omega) = \frac{1}{2} \sum_{n} \frac{1}{\beta_{n}} u_{n} *(x') u_{n}(x) e^{-i\beta_{n} |z-z'|}$$
(6)

where the summation symbol will now be used to indicate an integral over all continuum states as well as summation over bound waveguide modes. By construction  $G^0(\vec{r}, \vec{r}'; \omega)$  satisfies the differential equation

$$\left\{ \left( \frac{\partial^2}{\partial x^2} + \frac{\omega^2}{c^2} n_0^2(x) \right) + \frac{\partial^2}{\partial z^2} \right\} G^0(\vec{r}, \vec{r}'; \omega) = \delta(x-x') \delta(z-z')$$
 (7)

The full GF  $G(\vec{r}, \vec{r}; \omega)$  that satisfies

$$\left\{ \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial z^2} + \frac{\omega^2}{c^2} n_0^2(x) \right) + \frac{\omega^2}{c^2} \delta n^2(x,z) \right\} G(\vec{r}, \vec{r}'; \omega) = \delta(x-x') \delta(z-z')$$
 (8)

may then be determined by iteration, with the initial approximation to  $G(\vec{r}, \vec{r}'; \omega)$  being given by  $G^{O}(\vec{r}, \vec{r}'; \omega)$ ; thus

$$G(\vec{r}, \vec{r}'; \omega) = G^{0}(\vec{r}, \vec{r}'; \omega) + \int G^{0}(\vec{r}, \vec{r}''; \omega) \frac{\omega^{2}}{c^{2}} \delta n^{2}(\vec{r}''') G^{0}(\vec{r}'' \vec{r}'') d\vec{r}'''$$

$$+ \int \int G^{0}(\vec{r}\vec{r}''') \frac{\omega^{2}}{c^{2}} \delta n^{2}(\vec{r}''') G^{0}(\vec{r}'''\vec{r}'''') \frac{\omega^{2}}{c^{2}} \delta n^{2}(\vec{r}'''') G(\vec{r}'''\vec{r}''') d\vec{r}''' d\vec{r}''' + \dots$$
(9)

The scattered wave produced by the perturbed waveguide in response to an incident wave  $E^{O}$  can then be expressed using the full GF as

$$\delta E(\vec{r},\omega) = -\int G(\vec{r} \vec{r}';\omega) \frac{\omega^2}{c^2} \delta n^2(\vec{r}') E_y^0(\vec{r}') d\vec{r}'. \qquad (10)$$

In order to exhibit a calculation of an OTDR backscattered return using the GF approach in the simplest manner, we shall limit the present calculation to planar guides with perturbations  $\delta n^2(x,z)$  that can be factored as

$$\delta n^2(x,z) = \delta n^2(x) \cdot f(z) \qquad (11)$$

We shall first assume that the input pulse is Gaussian and that only one incident mode i is excited

$$E_{y}^{0}(\vec{r},t) = e^{i\omega_{0}t - (t-t_{0})^{2}/2\tau^{2}} -i\beta_{i}z \cdot N_{T}$$
 (12)

where  $N_{\tau}$  is a normalization factor for the input pulse. If input pulses are normalized to have equal energy, e.g.

$$\int E_{y}^{0}(x,z,t)^{*} E_{y}^{0}(x,z,t) dx dt = 1$$
 (13)

the normalization factor will be given by

$$N_{\tau} = \tau^{-1/2} \pi^{-1/4}. \tag{14}$$

To calculate the scattered pulse we decompose the initial pulse into its Fourier components (taking  $t_0 = 0$ )

$$E_{y}^{0}(\vec{r},\omega) = \frac{1}{2\pi} \int e^{-i\omega t} E_{y}^{0}(\vec{r},t)dt = \frac{e^{-(\omega-\omega_{0})^{2}\tau^{2}/2}}{\sqrt{2\pi}} \tau_{u_{1}}(x) e^{-i\beta_{1}z} N_{\tau}$$
 (15)

and propagate each frequency component  $\omega$  with the GF  $G(\vec{r}\ \vec{r}';\omega)$ . Using equation(10)and approximating  $G(\vec{r}\ \vec{r}';\omega)$  to lowest order by  $G^{0}(\vec{r},\ \vec{r}';\omega)$ , the scattered pulse can be expressed as

$$\delta E_{y}(\vec{r},t) = \int \int e^{i\omega t} d\omega \frac{\omega^{2}}{2ic^{2}} \sum_{n} \frac{1}{\beta_{n}} u_{n}^{*}(x') u_{n}(x) e^{-i\beta_{n}|z-z'|}$$

$$.\delta n^{2}(x) f(z') e^{-(\omega-\omega_{0})^{2}\tau^{2}/2} \tau u_{i}(x') e^{-i\beta_{i}z'} N_{\tau} dx' dz'.$$
(16)

Expanding each  $\beta_{\boldsymbol{n}}(\omega)$  around the central frequency  $\boldsymbol{\omega}_{\boldsymbol{0}}$  as

$$\beta_{\mathbf{n}}(\omega) \simeq \beta_{\mathbf{n}}(\omega_{\mathbf{0}}) + \frac{\partial \beta_{\mathbf{n}}}{\partial \omega} \Big|_{\omega_{\mathbf{0}}} \cdot (\omega - \omega_{\mathbf{0}}) + \dots$$

$$= \beta_{\mathbf{n}}^{\mathbf{0}} + \mathbf{v}_{\mathbf{n}}^{-1} \cdot (\omega - \omega_{\mathbf{0}}) + \dots$$
(17)

and retaining only  $\beta_n(\omega_0)$  and the first derivative term

$$\frac{\partial \beta_n}{\partial \omega} \Big|_{\omega_n} = \nu_n^{-1} \tag{18}$$

where  $\mathbf{v}_{n}$  is the modal group velocity, the expression for the scattered wave  $\delta E_{\mathbf{v}}$  can be written as

$$\delta E_y^{\frac{1}{2}} \simeq \frac{\Sigma}{n} e^{i\omega_0 t + i\beta_n^0} z \int e^{i(\omega - \omega_0)t} \frac{e^{-(\omega - \omega_0)^2 \tau^2/2}}{e^{-(\omega - \omega_0)^2 \tau^2/2}} \frac{\tau \omega_0^2}{2ic^2}$$

$$e^{\frac{\pm i v_n^{-1} (\omega - \omega_0) z}{\beta_n^0}} \frac{u_n(x)}{\beta_n^0} \cdot \varepsilon_{in} \cdot \eta(\beta_i \pm \beta_n) N_{\tau}$$
 (19)

where  $\epsilon_{\mbox{in}}$  and  $\eta$  are the transverse and longitudinal matrix elements of the perturbation given by

$$\varepsilon_{in} = \int u_n^*(x) \left[ \delta n^2(x) \right] u_i(x) dx$$
 (20)

and

$$\eta(\beta_i + \beta_n) = \int_{-\infty}^{\infty} e^{-i(\beta_i + \beta_n) z} f(z)dz$$
 (21)

and where Trefer to backward and forward scattered waves respectively.

The perturbations considered here lead in general to reflection, radiation loss, and mode-mixing. To obtain predictions of the backscattered OTDR signal, we must also account for several other sources of attenuation in the fiber such as Rayleigh scattering, intrinsic and extrinsic absorption, and curvature radiation losses (to be discussed in section IIIb). All of the latter may be incorporated into the GF approach by allowing the propagation constant for each mode to have an imaginary part

$$\beta_n \rightarrow \beta_n - i\alpha_n/2 . \tag{22}$$

proportional to the total attenuation

$$\alpha_n(z) = \alpha_n(z)_{RAYLEIGH} + \alpha_n(z)_{ABSORB} + \alpha_n(z)_{BEND}.$$
 (23)

The Rayleigh and absorption losses are nearly uniform throughout a given fiber while the curvature radiation loss, when applicable, is generally confined to a limited length of fiber.

### III. MODEL CALCULATION OF OTDR FROM BENDS

In this section we apply the formalism of section II to predict the OTDR return from bends in fibers. For purposes of illustration we will simplify the calculation by utilizing as our model a step index planar guide with a perturbation consisting of a bent region (possibly containing multiple loops) extending from z=a to z=a+L with a bend radius of curvature  $R_0$ . Use of the planar geometry allows us to demonstrate the principal physical effects associated with OTDR from bent fibers with a minimum of mathematical complexity. The methods employed are easily generalized to circular fibers at the expense of more tedious calculation.

For definiteness we choose the following values of parameters for the unperturbed guide: refractive index of the core  $n_1$  = 1.51; refractive index of the clad (assumed to be of infinite extent)  $n_2$  = 1.50; core width d = 10  $\mu$ m, center wavelength for the input pulse  $\lambda_0$  = 1 $\mu$ m. With this choice of parameters there will be a total of seven bound modes.

For gentle bends ( $R_0 >> d$ ) a bent section of guide may be considered as an equivalent straight guide<sup>2</sup> with a perturbation given by

$$\delta n^2(x) = 2 \times n_0^2(x)$$

$$f_0(z) = \frac{1}{R_0(z)} = \frac{1}{R_0} \theta(z-a) \theta(a+L-z). \tag{24}$$

For this case eqn. (19) yields

$$\delta E_{y} + (\vec{r}_{i}t) \approx \sum_{n} e^{i\omega_{0}t} \frac{1}{2ic^{2}} e^{i\beta_{n}z} \left[\frac{\omega_{0}^{2}}{2ic^{2}}\right] \epsilon_{in} \frac{u_{n}(x)}{\beta_{n}} \frac{i}{\left[\beta_{i} + \beta_{n}\right]}$$

$$x \left[e^{-\frac{1}{2}\left(t + \frac{a+L-z}{v_{n}} - \frac{a+L}{v_{i}}\right)^{2}/\tau^{2}} e^{-i\left(\beta_{i} + \beta_{n}\right)(a+L)}\right]$$

$$-e^{-\frac{1}{2}\left(t + \frac{a-z}{v_{n}} - \frac{a}{v_{i}}\right)^{2}/\tau^{2}} e^{-i\left(\beta_{i} + \beta_{n}\right)a} N_{T} \qquad (25)$$

(where we have omitted writing the superscript"o"on  $\beta_n^{0}$ 's). From this expression it can be seen that backward or forward scattered waves will appear to come from the front and rear of the perturbed region with appropriate time delays and phases.

The reason no scattered waves come from the interior of the perturbed region is that contributions to the scattered wave from the interior cancel out exactly leaving only the uncancelled front and rear contributions. In general scattered waves will be generated from within a perturbed region if the perturbation is not entirely uniform. On a microscopic scale such non-uniformity is essentially the mechanism which produces Rayleigh scattering. Inhomogeneities in this case are due to frozen in thermal fluctuations in

density and composition which result in fluctuations of the refractive index. A calculation of Rayleigh scattering can be carried out using the GF methods discussed above but will not be undertaken here.

When all processes have been included, the OTDR return from the bend will consist of backscattered Rayleigh radiation that has been diminished by curvature radiation and by localized radiation losses as the pulse transits the front and rear of the bend plus a "reflected pulse" that consists of backscattering into bound modes that will also appear to come from the front and rear of the bend. Due to the random nature of the frozen in fluctuations giving rise to Rayleight scattering, the reflected pulse and the Rayleigh backscattered pulse will not interfere. This may be seen by expressing the total backscattered power as

$$P_{TOT}^{(-)}(t) = \sum_{n} \frac{\beta_{n}}{\omega \mu_{0}} \int_{0}^{\pi} \left| \delta E_{n}^{(-)}(x,z,t) + \delta E_{n}^{(-)}(x,z,t) \right| >_{AV} dx$$

$$= P_{REF}^{(-)}(t) + \sum_{n} \frac{\beta_{n}}{\omega \mu_{0}} \int \delta E_{n}^{(-)}(x,t) < \delta E_{n}^{(-)}(x,z,t) > AV \quad dx + c.c.$$

$$+ \sum_{n} \frac{\beta_{n}}{\omega \mu_{0}} \int \left\{ \left[ E_{n}(-)(x,z,t) \right]^{2} > dx. \right\}$$
 (26)

Since the thermal average of  $\delta E_n^{(-)}$  is zero, Contributions to the OTDR backscattered pulse from Rayleigh scattering and from the reflected pulse will be simply additive

$$P_{TOT}^{(-)}(t) = P_{REF}^{(-)}(t) + P_{RAYL}^{(-)}(t)$$
 (27)

In the following sections we will discuss each of these contributions separately. In section IV numerical results using the above model for various curvature radii and pulse lengths will be discussed.

## IIIa. TRANSITION LOSS

The relative power that is radiated away as the input pulse passes the perturbed region can be calculated as

$$\frac{\delta P_{TR}(t)}{P_{o}} = \int_{0}^{n_{2}k_{o}} d\beta_{k} \left[ \frac{\delta P_{k}^{+} + \delta P_{k}^{-}}{P_{o}} \right]$$
 (28)

where

$$\delta P_{k}^{\pm}/P_{0} = \frac{1}{P_{0}} \int dx \, \delta E_{y}^{\pm} (k) \, \frac{i}{\omega \mu_{0}} \frac{\partial}{\partial z} \, \delta E_{y}^{\pm} (k)$$
 (29)

are the forward and backward radiation losses and  $\delta E_y^{\dagger}$  (k) is the integrand of eqn. (25) for the continuum contributions. Due to the denominator  $(\beta_i \pm \beta_k)^{-1}$  in eqn. (25) backward radiation will be much smaller than forward radiation and can be neglected. Using the expression for  $\delta E_y^{\dagger}(k)$  for forward scattering from eqn. (25) and performing the x integration then yields

$$\frac{\delta P_{TR}(t)}{P_{0}} = \frac{k_{0}^{4}}{4\beta_{i}} \int_{0}^{n_{2}k_{0}} d\beta_{k} \frac{|\epsilon_{ik}|^{2}}{(n_{2}^{2}k_{0}^{2} - \beta_{k}^{2})^{2}(\beta_{i} - \beta_{k})^{2}}$$

$$x \left[ f_{ik}^{2} + g_{ik}^{2} - 2 f_{ik}^{g} g_{ik} \cos ((\beta_{i} - \beta_{k})L) \right]$$
 (30)

where 
$$f_{ik} = e^{-\left[t-(a-z)v_k^{-1} - av_i^{-1}\right]^2/2\tau^2} \cdot N_{\tau}$$

and 
$$g_{ik} = e^{-\left[t - (a+L-z)v_k^{-1} - (a+L)v_i^{-1}\right]^2/2\tau^2} \cdot N_{\tau}$$
 (31)

represent the radiation pulses coming from the front and rear of the bend.

If we consider the L dependence of the forward radiation loss, there are two limiting regimes. In the first L >>  $(\beta_i - \beta_k)^{-1}$  for all  $\beta_k$  in the range  $n_2 k_0 > \beta_k > 0$ . For this case the rapidly oscillating cross term proproportional to  $\cos((\beta_i - \beta_k)L)$  can be set equal to zero and the forward radiation can be considered as being lost in two steps, the first as the pulse transits the beginning of the bend at z=a and the second as it passes the end of the bend at z=a+L. For this case (after factoring out the bracketed term representing the pulse shape) the transition loss  $T_i$  is given by

$$T_{i} = \frac{k_{o}^{4}}{4\beta_{i}} \int_{0}^{n_{2}k_{o}} \frac{d\beta_{k}}{(n_{2}^{2}k_{o}^{2} - \beta_{k}^{2})^{\frac{1}{2}}} \frac{|\epsilon_{ik}|^{2}}{(\beta_{i}^{-\beta_{k}})^{2}}$$
(32)

In the second regime  $L(\beta_i - \beta_k)^{-1} \lesssim 10^2 - 10^3$  the cross term may not be neglected and there is the possibility of radiation fields from the front and back of the bend interfering. For this case  $f_{ik} \sim g_{ik}$  and the integration over all radiation modes is given by

$$2T_{i} = \frac{k_{o}^{4}}{4\beta_{i}} \int_{0}^{n_{2}k_{o}} d\beta_{k} \frac{\left|\varepsilon_{ik}\right|^{2}}{\rho_{k}(\beta_{i}-\beta_{k})^{2}} \cdot 2(1-\cos(\beta_{i}-\beta_{k})L))$$

$$= \frac{k_{0}^{4}}{4\beta_{i}} \int_{0}^{n_{2}k_{0}} d\beta_{k} \left[ \frac{4 \sin^{2}((\beta_{i} - \beta_{k})^{L})}{(\beta_{i} - \beta_{k})^{6}} \right] \left[ \frac{16\Delta^{4}\cos^{2}\kappa_{i}d \sin^{2}\sigma_{i}d N_{e}^{2}\rho_{k}}{(\beta_{i} + \beta_{k})^{4}\pi \left[\rho_{k}^{2}\sin^{2}\sigma_{k}d + \sigma_{k}^{2}\cos^{2}\sigma_{k}d\right]} \right]$$

with

$$\rho_k^2 = (n_2^2 k_0^2 - \beta_k^2), \sigma_k^2 = (n_1^2 k_0^2 - \beta_k^2), \kappa_i^2 = (n_1^2 k_0^2 - \beta_i^2)$$

$$\Delta^2 = k_0^2 (n_1^2 - n_2^2), N_e = (d + \gamma_n^{-1})^{-1/2},$$

$$\gamma_{n} = (\beta_{n}^{2} - n_{2}^{2} k_{o}^{2})^{1/2}. \tag{33}$$

An approximate value for this integral may be obtained by assuming that the slowly varying second factor ( $\Xi F$ ) can be taken to be roughly constant over the region where the first factor is a maximum ( $\beta \sim \beta *_{\sim} n_2 k_0$ ). With this assumption we obtain an upper bound for the transition loss

$$2T_{i} \sim \frac{k_{o}^{4}}{4} \frac{\pi}{2 \cdot 5!} \left[ \frac{105}{32} \delta_{i}^{-9/2} - A(1 - C_{2}(\delta_{i}L) - S_{2}(\delta_{i}L)) \right]$$

$$-B(C_{2}(\delta_{i}L) - S_{2}(\delta_{i}L)) - C_{e} \left( \sin(\delta_{i}L) + \cos(\delta_{i}L) \right) +$$

$$C_{o}(\sin(\delta_{i}L) - \cos(\delta_{i}L)) \right] \cdot F(\beta^{*}) \qquad (34)$$
where
$$\delta_{i} = \beta_{i} - n_{2}k_{o}, C_{2} \text{ and } S_{2} \text{ are Fresnel integrals, and}$$

$$A = 105/32 \delta_{i}^{-9/2} - \frac{15}{4} L^{2} \delta_{i}^{-5/2}$$

$$+ 5/2 L^{4} \delta_{i}^{-1/2}$$

$$B = -75/16 L \delta_{i}^{-7/2} + 5/2 L^{3} \delta_{i}^{-3/2} + L^{5} \delta_{i}^{1/2}$$

$$C_{e} = L^{1/2}/\sqrt{2\pi} \left(105/16 \delta_{i}^{-4} - 3L^{2} \delta_{i}^{-2} - L^{4}\right)$$

$$C_{o} = L^{1/2}/\sqrt{2\pi} \left(5L \delta_{i}^{-3} - 2L^{3} \delta_{i}^{-1}\right). \qquad (35)$$

For the waveguide we have chosen as an example the  $\delta_i$ 's are of the order  $\delta_i \sim 10^4 \text{ m}^{-1}$ . The dependence of  $T_i$  on mode number will thus be given roughly by  $T_i \sim \delta_i^{-9/2}$ .

The calculation of transition loss given above is idealized to the extent that we have assumed an infinite cladding. For a finite clad any radiation that leaves the core region is effectively absorbed locally. The transition loss formula without the interferences term given by eqn. (25) would thus be more appropriate. Likewise the assumption of the bent guide as an equivalent straight guide obscures the fact that a guide may satisfy

the condition for interference to be important while the front of the bend may be topologically "far" from the rear of the bend due to looping. An additional constraint that L << R $_{0}$  should thus be imposed to further limit the domain where the interference term is important.

### IIIb OTDR FROM BENDS INCLUDING CURVATURE LOSS

Before the Rayleigh scattering contribution to the OTDR return can be obtained for bend perturbations, we must first incorporate an additional loss mechanism due to curvature radiation (tunneling loss) that is not accounted for within lowest order GF theory and that must be specifically included in the imaginary part of each propagation constant  $\beta_n$ . The origin of this curvature loss is discussed below.

If we view the refractive index profile as a quantum mechanical potential  $V_{(x)} = -k_o^2 n^2(x)$  then the perturbation  $\delta V^2 = -k_o^2 \frac{x}{R} n_o^2(x)$  will transform the step index potential as indicated in fig. 1.

It can be seen that all of the former bound states now have the possibility of tunneling through the lowered potential carrier to continuum states and calculation of this tunneling rate will yield a curvature loss  $\alpha^{i}_{RAD}$  proportional to

$$e^{-\frac{2}{3}R\gamma_{i}^{3}/\overline{\beta}^{2}} \text{ where } \gamma_{i}^{2} = \beta_{i}^{2} - n_{2}^{2}k_{0}^{2} \text{ and } \overline{\beta} = n_{1}k_{0}.$$
 (36)

Including both the curvature loss and the transition loss, the total backscattered signal due to Rayleigh scattering can be calculated for one incident mode  $\underline{i}$  as

$$\frac{P(-)}{P_0} RAYLEIGH = \alpha_{RAYLEIGH} \cdot \sum_{\infty}^{\infty} e^{-(t-(z'-z)/v_i-z'/v_0)^2/\tau^2}$$

$$\times \begin{cases} \theta(a-z') \exp(-2\alpha_{TOT}z') \end{cases}$$
(37)

+ 
$$(1-T_i-R_i)\theta(z'-a)\theta(a+L-z')$$
  $= \frac{-2\alpha}{101} z' = \frac{-2\alpha^i}{101} RAD^{(z'-a)}$ 

$$+(1-T_i-R_i)^2\theta(z'-(a+L)) e^{-2\alpha_{TOT} z'} e^{-2\alpha_{RAD}^i L}$$
 dz

where T  $_{i}$  and R  $_{i\,th}$  are the transition loss and reflected power for the i  $^{i}$  mode, where

$$\alpha$$
TOT =  $\alpha$ ABSORB +  $\alpha$ RAYLEIGH (38)

are taken to be independent of mode number,

and  $\alpha_{RAD}^{n}$  is given for the step index guide  $^{4}$  as

$$\alpha_{RAD}^{n} = \frac{\gamma_{n}^{2}}{\beta_{n}(1+\gamma_{n}a)} \frac{\kappa_{n}^{2}}{(n_{1}^{2}-n_{2}^{2})k_{o}^{2}} e^{2\gamma_{n}a} e^{-2/3(\gamma_{n}^{3}/\beta_{n}^{2})R}$$
(39)

with

$$\xi = \frac{3}{8} \frac{(n_1^2 - n_2^2)}{n_1^2} \tag{40}$$

a geometrical factor to approximate the fraction of Rayleigh scattered power that is backscattered into the guide  $^5$ . The integrals appearing in this expression can all be expressed analytically in terms of error functions.

From the expression (39) for  $\alpha_{RAD}^{n}$  it can be seen that the curvature loss depends exponentially upon both  $R_{o}$  and the mode number n. The step index guide we have chosen as an example yields  $(\gamma_{6})^{3} \sim (\gamma_{0})^{3}/12$ ; tunneling losses for the weakly bound modes can thus be many orders of magnitude greater than those of tightly bound modes.

### IIIC DIRECT REFLECTIONS AND EFFECTS DUE TO GRADUAL BEND ONSET

Due to mechanical stiffness, the transition from a straight guide to a curved section of guide will not, in general, occur abruptly, but will change gradually over some finite distance  $\delta = 2\pi/q$  as indicated in fig. 2. In this subsection we consider the effect of a continuous transition region (curvature radius changes from  $R^{-1}=0$  to  $R^{-1}\neq 0$  over a finite distance) on the OTDR return.

We first consider a transition model with

$$R^{-1}(z) = \frac{1}{2} \left[ th(q(z-a)) + th(q(a+L-z)) \right]$$
 (41)

which yields for the longitudinal matrix element

$$\eta(p_{\pm}) = \int_{\infty}^{\infty} R^{-1}(z) e^{-ip_{\pm}z} dz$$

$$= i e^{-ip_{\pm}a} \left[ e^{-ip_{\pm}L} - 1 \right] \left\{ \frac{\pi}{q} \frac{\sinh(p_{\pm}\pi/2q)}{\left[ \cosh(p_{\pm}\pi/q) - 1 \right]} \right\}$$
(42)

where  $p_{+} = \beta_{1} + \beta$ . In the point limit  $\delta \rightarrow 0$ ,  $\eta \rightarrow \eta_{0}$ , where

$$\eta_0(p_+) = \frac{i}{p_+} e^{-ip_{\pm}a} \left[ e^{-ip_{\pm}L} - 1 \right]$$
 (43)

is the longitudinal matrix element used in eqn. (25) For the case of backward scattering where  $q \ll p_{\perp}$ , eqn. (42) yields

$$\eta(p_{+}) \approx i e^{-ip_{+}a} \left[ e^{-ip_{+}L} - 1 \right] \frac{\pi}{q} e^{-p_{+}\pi/2q}$$

$$= \eta^{0}(p_{+}) \left[ \frac{p_{+}\pi}{q} e^{-p_{+}\pi/2q} \right] \tag{44}$$

which goes to zero exponentially, suppressing reflected waves. Only if  $\delta < \lambda_0$  will backward scattered waves be significant. For forward scattering it is possible for q to be comparable with p\_ (for the guide of section III,  $q = p\_\sim 10^4 \Rightarrow \delta \sim 2\pi \times 100 \ \mu m$ ) in which casen can be of the same order as  $\eta_0$ .

In a second model for the transition we take

$$\frac{1}{R(z)} = \begin{cases}
\frac{1}{R_0} & \frac{(1-\cos(q(z-a)))}{2}, & a < z < a + \pi/q \\
\frac{1}{R_0}, & a + \pi/q < z < a + L - \pi/q \\
\frac{1}{R_0} & \frac{(1-\cos(q(a+L-z)))}{2}, & a+L - \pi/q < z < a+L
\end{cases} \tag{45}$$

yielding

$$\eta(p) = \frac{e^{-ipa}}{2R_0} \frac{q^2}{ip(p^2 - q^2)} \left[ e^{-ipL} (1 + e^{ip\pi/q}) - (1 + e^{-ip\pi/q}) \right]$$
(46)

which has the same  $q \to \infty$  point limit as the first model. For backward scattering and  $q \ll p_+$ , the overall magnitude of  $\eta(p_+)$  is down by a factor  $q^2/P_+^2$  over  $\eta_0(p_+)$ , yielding a drastically reduced reflected pulse. For the reflected pulse to be of the same order as the Rayleigh backscattered pulse,  $\delta$  would have to be of the same order as  $\lambda_0$ , i.e. smaller than the width of the guide.

If the second model is changed to allow a uniform series of a sinusoidal bends ie.,

$$\frac{1}{R(z)} = \frac{1}{R_0} \frac{(1-\cos q(z-a))}{2}, \ a < z < a + \frac{2N\pi}{q}$$

$$N = 1, 2, 3...$$
(47)

we find

$$\eta(p) = e^{-i\bar{p}a} \left(e^{-ip2\pi N/q} - 1\right) \frac{q^2}{ip(p^2 - q^2)}$$
 (48)

which for N=1 agrees with the second model when  $L = 2\pi/q$  and is similar in form to the single bend of the second model for N>1.

## IV COMPUTED RESULTS

To illustrate the effects of bend radius of curvature and pulse length on OTDR returns as calculated for the model of section III, we have plotted in figs. 3 through 10 the OTDR return pulse vs. time for bends having curvature radii of 10 cm and .56 cm, and pulse widths of 10 ns and 100 ns. For these curves we have taken the longitudinal matrix element to be  $\eta = \eta_0$  and have assume reflections to be zero. The bend length L and the position of the bend onset a have been taken to be L = 3.5m and a = 10 m respectively.

The scattering coefficient for Rayleign scattering and the absorption coefficient for impurity absorption have been taken as  $\alpha_{RAYLEIGH}$  = .77 db/km and  $\alpha_{ABSORB}$  = .54 db/km respectively. For figures 3 through 6 the waveguide is assumed to be "uniformly" illuminated with an input field given by

$$u_{in} = \frac{1}{2} (u_{0}(x) + u_{2}(k) + u_{4}(x) + u_{6}(x))$$

$$= \sum_{i} a_{i} u_{i}$$
with
$$\begin{cases} a_{i} = 1/2, & i \text{ even} \\ a_{i} = 0, & i \text{ odd} \end{cases}$$
(49)

The inclusion of more than one input mode in eqn. (49) leads to a modification of eqn. (28) which represented the transition loss for one input mode, that includes new cross terms

$$\frac{P_{TR}(t)}{P_0} = \frac{k_0^4}{4\bar{\beta}_{in}} \int_0^{r_2 k_0} \frac{d\beta_k}{(n_2^2 k_0^2 - \beta_k^2)^{\frac{1}{2}}} \sum_{i, j} \frac{\epsilon_{ik} \epsilon_{jk} * a_i a_j^i}{(\beta_i - \beta_k)(\beta_j - \beta_k)}$$

$$x \left\{ \left[ f_{ik}^2 + g_{ik}^2 - 2 f_{ik} g_{ik} \cos(\beta_i - \beta_k) L \right] \delta_{ij} \right\}$$

where  $\overline{\beta}_{in}$  =  $(\beta_0 + \beta_2 + \beta_4 + \beta_6)/4$ .

For the off-diagonal terms in eq. (50) to be important the wave packets for each pair of modes, as given by eqn. (31) must overlap. If the onset length a is large and the group velocities for the various modes are different enough, the overlap products will be very small. In order to keep the present calculation as simple as possible we have assumed that the length a and the dispersion in group velocities are large enough to enable the off-diagonal terms be neglected.

Figures 3 and 4 indicate the behavior of the OTDR return for the case  $R_0$  = 10 cm where transition loss is the dominant loss mechanism. In figure 3 the pulse width = 10 ms is smaller than the temporal extent of the bend  $t_b = \frac{2L}{v_0} = 35$  ms while in figure 4 the pulse width is larger (we note that since the abscissa represents the round trip time, the front and rear of the bent section appear at t = 100 ms and t = 135 ms).

Since the return pulse behaves roughly as  $P \propto e^{-\alpha} eff^Z$  we have also plotted the derivative of this curve to indicate an effective loss rate  $\alpha_{eff}$ . The curve for  $\alpha_{eff}$  in figure 3 illustrates the transition loss from the front and rear of the bend for  $\tau \leq t_h$ .

Figures 5 and 6 illustrate the case of uniform illumination for  $R_0$  = .56 cm where curvature radiation is the dominant loss mechanism. Since the input power is equally distributed over the four symmetric modes while the outermost modes 4 and 6 can radiate their power away over a very short distance, approximately half of the input power ( $\sim$ 3db) is lost in a very short time after passing the onset of the bend if the pulse width is small (fig. 5,  $\tau$ = 10 ns) or over a proportionately longer time for longer pulses (fig. 6, t= 100 ns). (We note that the extra wiggles in the curves for  $\alpha_{\rm eff}$  in figures 5 and 6 are an artifact due to numerical differentiation and would be absent in a more exact evaluation).

To illustrate the dependence of transition loss and curvature radiation loss on mode number we have plotted in figures 7 through 10 the OTDR return from the model guide of section III excited by a pulse consisting of equal weights of

u<sub>2</sub> and u<sub>4</sub> (curve B)

 $u_4$  and  $u_6$  (curve C).

For the case of  $R_0$  = 10 cm, shown in figures 7 and 8 where transition loss dominates, it can be seen that only the least tightly bound mode 6 encounters an appreciable transition loss at z=a and z=a+L. The case  $R_0$  = .56 cm, where curvature radiation loss dominates, is shown in figures 9 and 10. Since

 $^{\alpha}_{6}$  RAD  $^{\sim}$  2.3 x  $^{10^{9}}$  db/km,  $^{\alpha}_{4}$  RAD  $^{\sim}$  1.4 x  $^{10^{4}}$  db/km, and  $^{\alpha}_{2}$  RAD  $^{\sim}$  .2 db/km,only the two outermost modes are affected to an appreciable extent. Mode 6 is lost entirely within a very short distance ( $^{\sim}10^{-5}$ m) while mode 4 is only fractionally depleted in traversing the bend. The sharp dropoff in curve C of figs. 9 and 10 at

t = 100 ns is due to the rapid loss of mode 6 input power.

In figures 11 and 12 we have illustrated the OTDR return for the case where  $\eta = \eta_0$  and reflected pulses are not suppressed.

## V CONCLUDING REMARKS

We have presented a theory of OTDR from weak static perturbations in optical fibers, utilizing a time-dependent Green's function formulation. The formulae we have obtained incorporate the effects of direct reflection and transition loss. The theory also incorporates uniform attenuation from absorption and scattering, as well as curvature radiation losses (when applicable). We have applied the theory to examine the OTDR signal (and its time derivative) from fiber bends as a function of bend length and radius, and the dependence on mode number and pulsewidth.

Our calculations for a simplified slab guide model demonstrates that transition losses dominate for large radius bends, while curvature losses dominate for small radius bends. In either case, if the spatial pulse width is much larger than the length of the bent region, the loss snows up as a single drop in the OTDR signal. As expected, the size of the loss is very sensitive to mode number. When the pulse width is short compared to the bent region, separate features due to the front and end of the bend may be observed in certain instances. Moreover, if the bend region occurs abruptly, then peaks due to reflections can be observed in OTDR with short pulses. If the bend onsets gradually, however, then reflection effects will be suppressed.

Experiments to date have indicated agreement with several general features mentioned above, such as the overall loss at the bend and the sensitivity on the spatial mode patterned launched in the fiber. However, further refinements in both the theoretical model (extension to circular fibers) as well as the experimental techniques (better signal-to-noise ratio, availability of shorter pulses) are required before a quantitative comparison between theory and experiment can be carried out.

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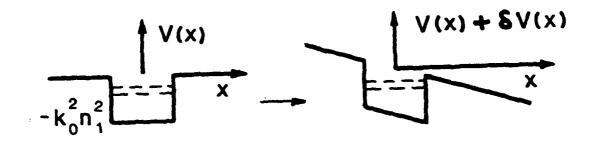


Fig. 1. Effect of bend perturbation on waveguide "potential well".

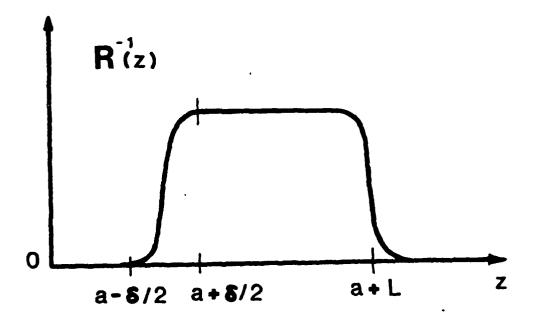


Fig. 2. Inverse of curvature radius  $R^{-1}(z)$  versus Z.

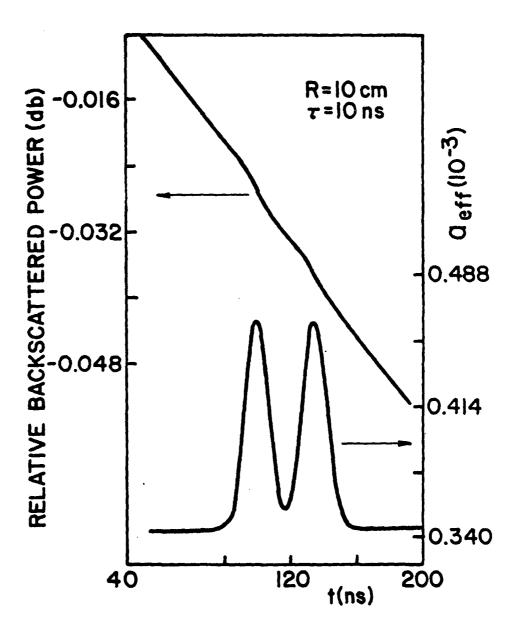


Fig. 3. Upper curve is the  $\log_{10}$  of the intensity of the OTDR return pulse versus time for "uniform excitation"; lower curve is the derivative of the upper curve in units of m<sup>-1</sup> (m<sup>-1</sup> = 4.343 x  $10^3$ db/km).

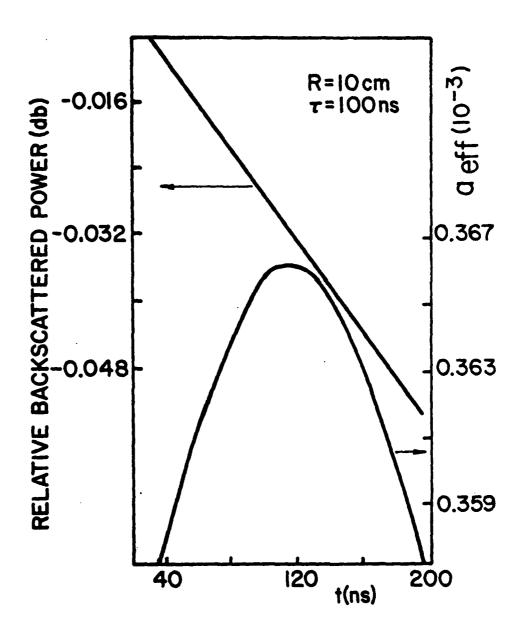


Fig. 4. Same as fig. 3, but for other choices of parameters.

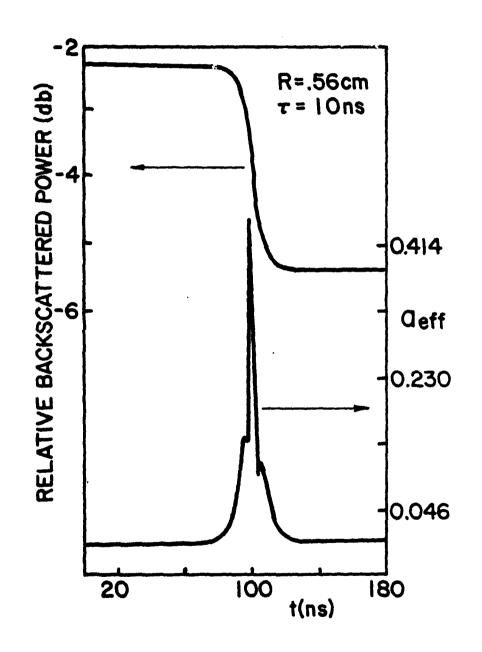


Fig. 5. Same as fig. 3, but for other choices of parameters.

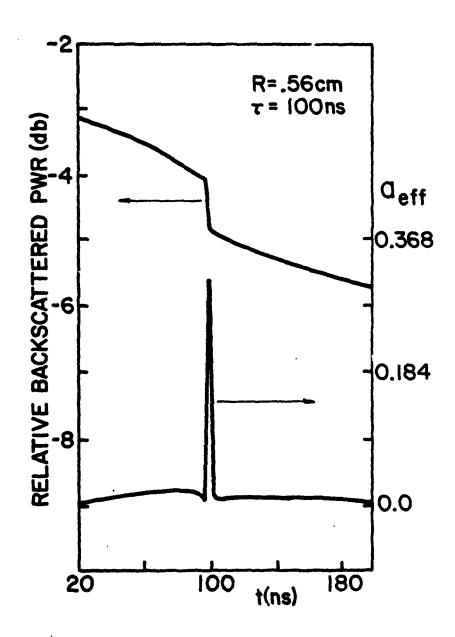


Fig. 6. Same as fig. 3, but for other choices of parameters.

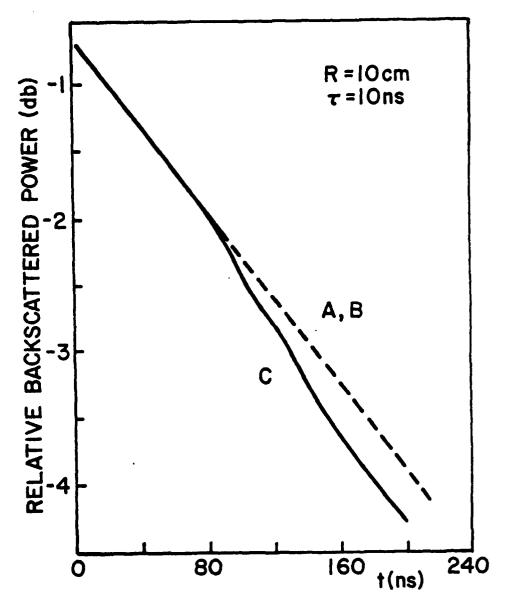


Fig. 7. Log<sub>10</sub> of the intensity of the OTDR return pulse vs time: Curve A results from initial excitation of modes 0 and 2 (in units of .016 db); Curve B, modes 2 and 4 (in units of .016 db); curve C, modes 4 and 6 (in units of .016 db).

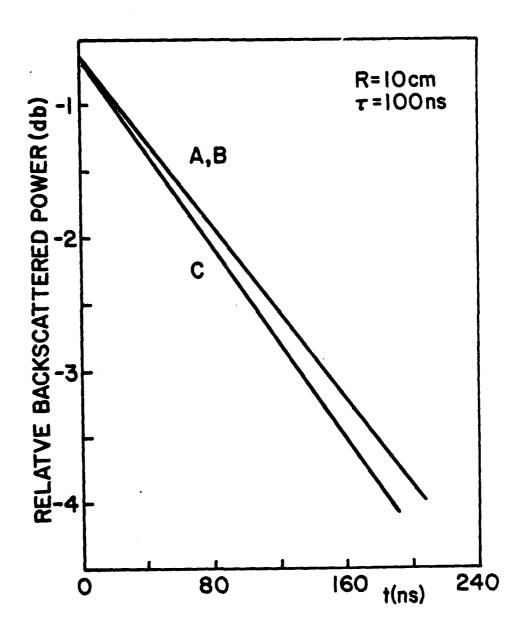


Fig. 8. Same as fig. 7, but for other choices of parameters.

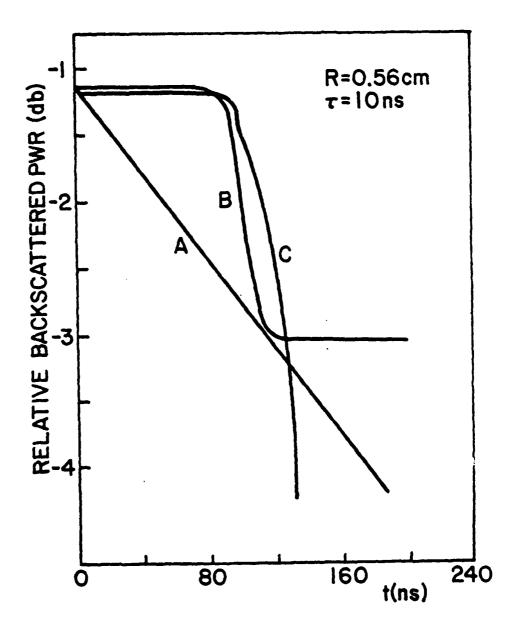


Fig. 9. Same as fig. 7, but for other choices of parameters. Also units are changed as follows:

curve A in units of .016 db, curve B in units of 1.6 db,

curve C in units of 20. db.

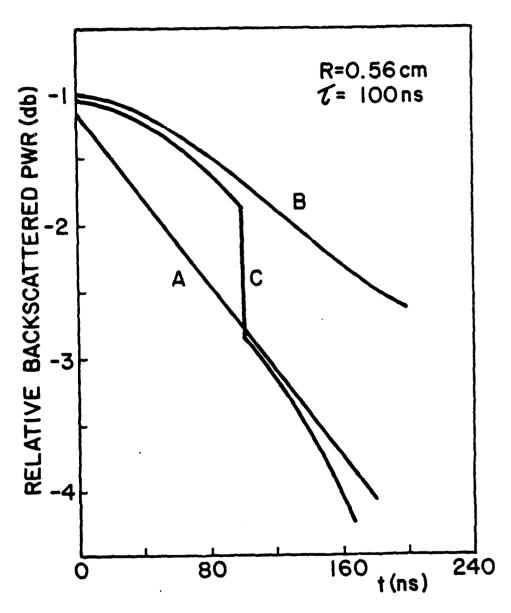


Fig. 10. Same as fig. 7, but for other choices of parameters. Also units are changed as follows:

curve A in units of .016 db, curve B in units of 1.6 db,

curve C in units of 3.2 db.

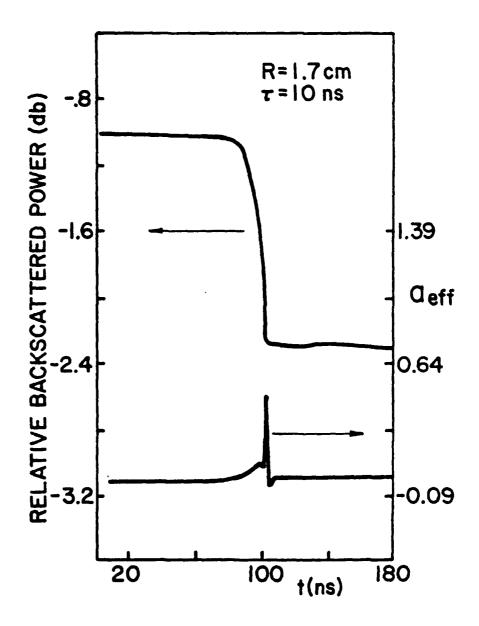


Fig. 11. Same as fig. 3, but with direct reflection included (as well as other choices of parameters).

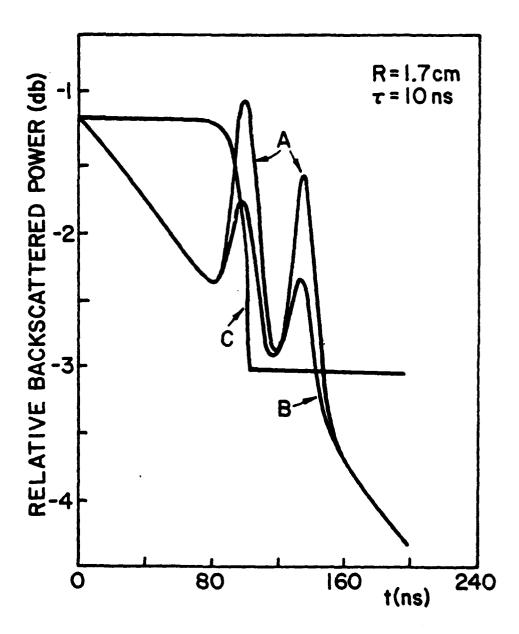


Fig. 12. Same as fig. 7 but with direct reflection included (as well as other choices of parameters). Also units are changed as follows: curves A and B in units of .016 db, curve C in units of 1.6 db.

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